

Automated soil mapping based on Machine Learning: towards a soil data revolution

Presented at the [DSM 2016 conference](#)

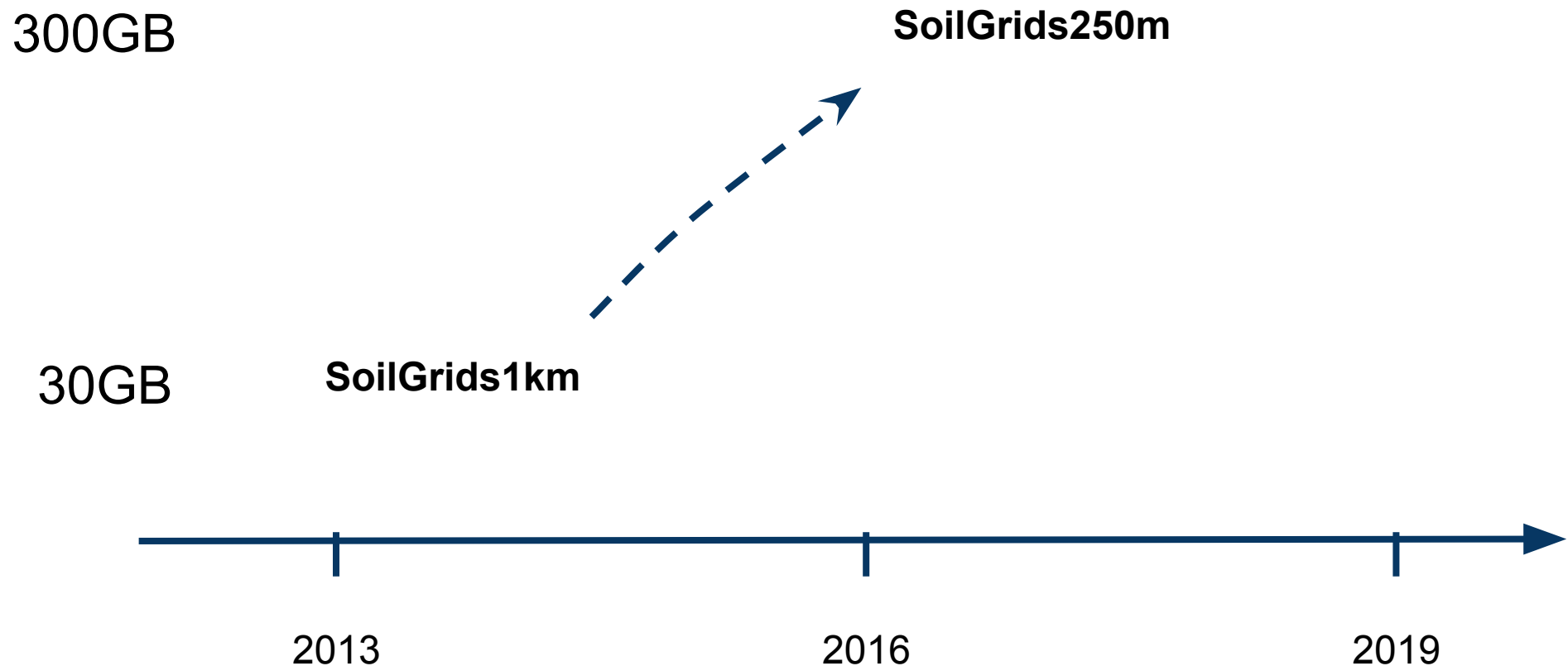


World Soil Information

T. (Tom) Hengl <tom.hengl@isric.org>



Since 2013, we have been revising SoilGrids



The new system:

300GB

SoilGrids250m

30GB

SoilGrids1km

1. More points
2. More covariates
3. 16x more pixels
4. MLA (ensemble)
5. Computing optimization
6. Higher accuracy

2013

2016

2019



World Soil Information

SoilGrids250m: global gridded soil information based on Machine Learning

Tomislav Hengl¹, Jorge Mendes de Jesus¹, Gerard B.M. Heuvelink¹, Maria Ruiperez Gonzalez¹, Milan Kilibarda², Aleksandar Blagotić³, Wei Shangguan⁴, Marvin N. Wright⁵, Xiaoyuan Geng⁶, Bernhard Bauer-Marschallinger⁷, Mario Antonio Guevara⁸, Rodrigo Vargas⁸, Robert A. MacMillan⁹, Niels H. Batjes¹, Johan G.B. Leenaars¹, Eloi Ribeiro¹, Ichsani Wheeler¹⁰, Stephan Mantel¹, and Bas Kempen¹

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⁸University of Delaware, Newark DE, USA

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Abstract. This paper describes the technical development and accuracy assessment of the most recent and improved version of the SoilGrids system at 250 m resolution (June 2016 update). SoilGrids provides global predictions for standard numeric soil properties (organic carbon, bulk density, Cation Exchange Capacity (CEC), pH, soil texture fractions and coarse fragments) at seven standard depths (0, 5, 15, 30, 60, 100 and 200 cm), in addition to predictions of depth to bedrock and distribution of soil classes based on the World Reference Base (WRB) and USDA classification systems (ca. 280 raster layers in total). Predictions were based on ca. 150,000 soil profiles used for training and a stack of 158 remote sensing-based soil covariates (primarily derived from MODIS land products, SRTM DEM derivatives, climatic images and global landform and lithology maps), which were used to fit an ensemble of machine learning methods — random forest and gradient boosting and/or multinomial logistic regression — as implemented in the R packages ranger, xgboost, nnet and caret. The results of 10-fold



SOILGRIDS

A system for automated global soil mapping

www.soilgrids.org



World Soil Information

SoilGrids are heavily based on:

- **OpenStreetMap**
- **OpenWeatherMap**
- **Wikipedia**
- **Global Biodiversity Information Facilities**



Important info about SoilGrids

- 1. Open Data license**
- 2. Updatable maps**
- 3. Code on Github (reproducibility)**
- 4. Diversity of access (FTP, WCS, REST API)**
- 5. ... moving towards crowdsourcing**



1. Open Data license



ODC Open Database License (ODbL) Summary

This is a human-readable summary of the [ODbL 1.0 license](#). Please see the disclaimer below.

MORE INFORMATION

- Introduction to Open Data
- Open Definition for Data
- Quick guide to making data open
- Open Data Handbook

You are free:



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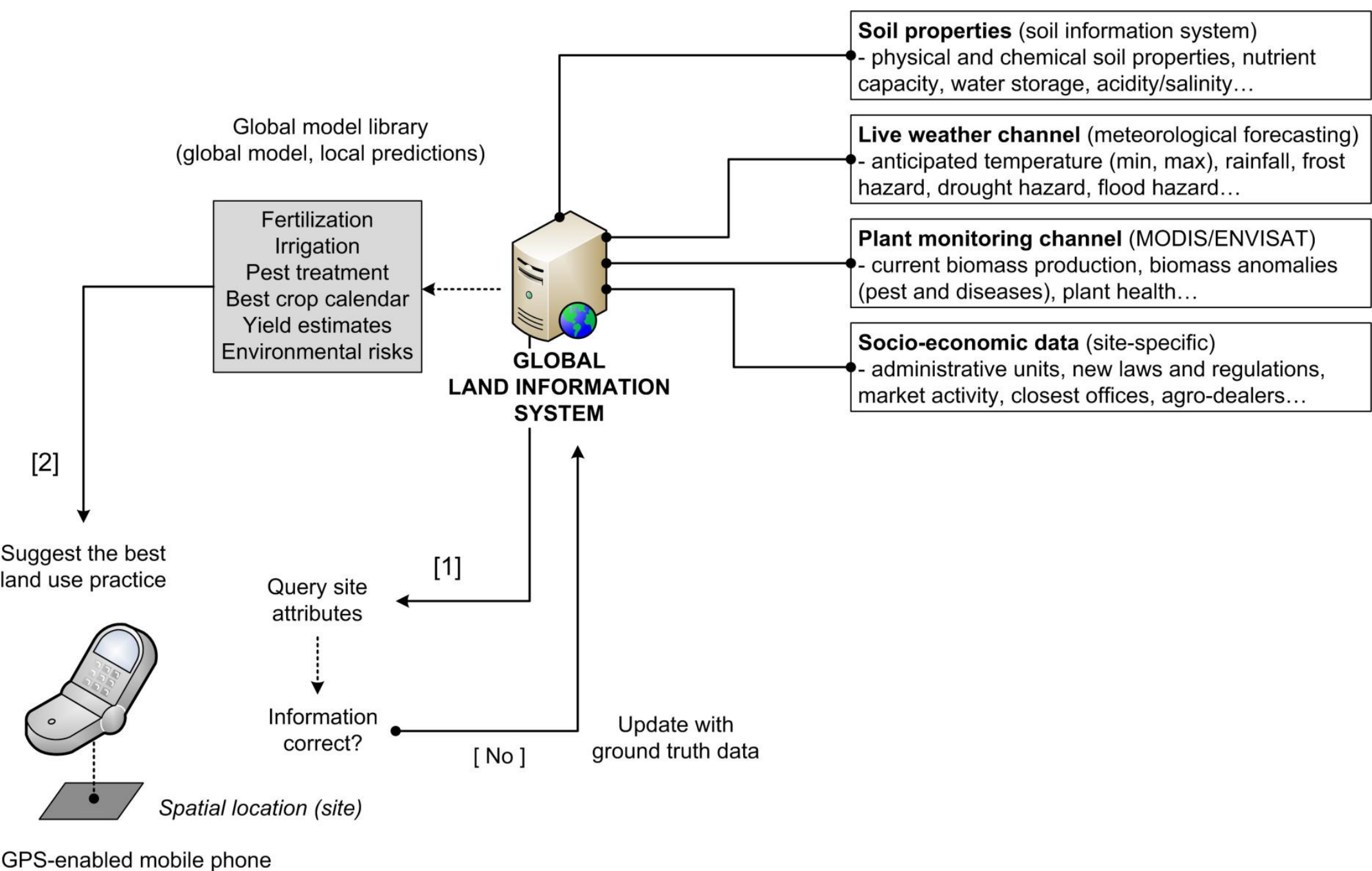
This is not a license. It is simply a handy reference for understanding the ODbL 1.0 — it



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2. Versioning (automated mapping system)





3. Reproducibility / open code



<https://github.com/ISRICWorldSoil/>

ISRICWorldSoil / SoilGrids250m

Unwatch 10 Star 7 Fork 2

Code Issues 4 Pull requests 0 Wiki Pulse Graphs Settings

Global spatial predictions of soil properties and classes at 250 m resolution — Edit

103 commits 1 branch 0 releases 4 contributors

Branch: master New pull request Create new file Upload files Find file Clone or download

thengl	Updated observed classes for SoilGrids	Latest commit ba7c9c2 16 days ago
grids	Updated observed classes for SoilGrids	16 days ago
profiles	Fixed bug in import of NamSOTER / CanSIS points	19 days ago
.gitignore	Preview PSCS predictions in QGIS	2 months ago
README.md	Update README.md	21 days ago

README.md

SoilGrids250m

Global spatial predictions of soil properties and classes at 250 m resolution



What can you find on this github repository:

- R scripts documenting processing steps,
- Sample code explaining the modelling framework,
- Functions for Cross-validation of ensemble models with examples,
- Examples of predictions. outputs and visualizations.



World Soil Information

SoilGrids inputs:

- **ca 150,000 points ("World's largest" compilation of soil profile / soil sample data sets)** based on national and international datasets from over 45 countries.
- **40TB repository of MODIS land products, climatic images, DEM derivatives, geological and geomorphological data** (all at 250 m resolution)
- ISRIC's international network that can cross-check and validate spatial prediction patterns / values.



Data holdings in WoSIS 2

(December 2015)

- About 98,000 unique profiles
- Some 76,000 profiles are georeferenced within defined limits
- Number of measured data for each property varies between profiles with depth, generally depending on the purpose of the initial studies
- Source data based on diverse (inter)national standards
- Generally, limited quality information provided with the source (analytical) data

Lineage:

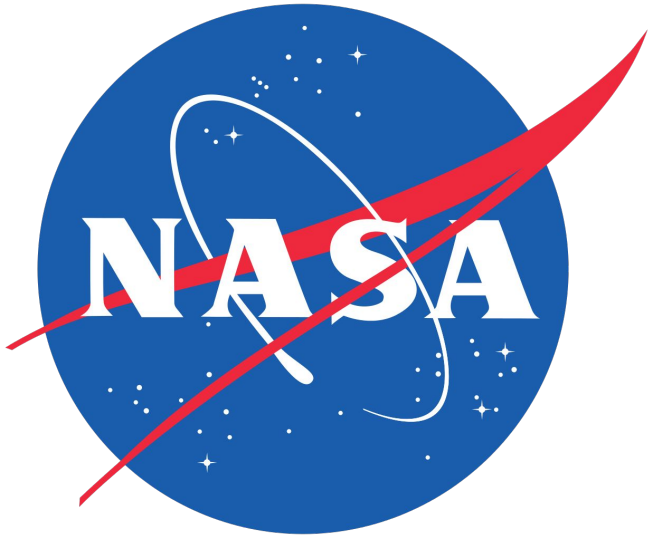
- Datasets, reports & maps

Soil observations and measurements:

- Feature (georeferenced profiles & layers)
- Attribute (x-y-z-t, map, class, site, layer-field, layer-lab)
- Method
- Value, including units of expression



SoilGrids are possible mainly thanks to:



World Soil Information

And thanks to: AfSIS project

Bill & Melinda Gates Foundation

Business Operation

Bill & Melinda Gates Foundation is one of the largest private foundations in the world, founded by Bill and Melinda Gates. It was launched in 2000 and is said to be the largest transparently operated private foundation in the world.

[Wikipedia](#)

Nonprofit category: Private Grantmaking Foundations

Founded: 2000

Assets: 36.79 billion USD (2010)

Income: 53 billion USD (2010)

Founders: [Melinda Gates](#), [Bill Gates](#)



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Also thanks to:



Center for International Forestry Research



WOODS HOLE
RESEARCH CENTER

UN-REDD
PROGRAMME



Food and Agriculture
Organization of the
United Nations



Empowered lives.
Resilient nations.



The United Nations Collaborative Programme
on Reducing Emissions from Deforestation
and Forest Degradation in Developing Countries



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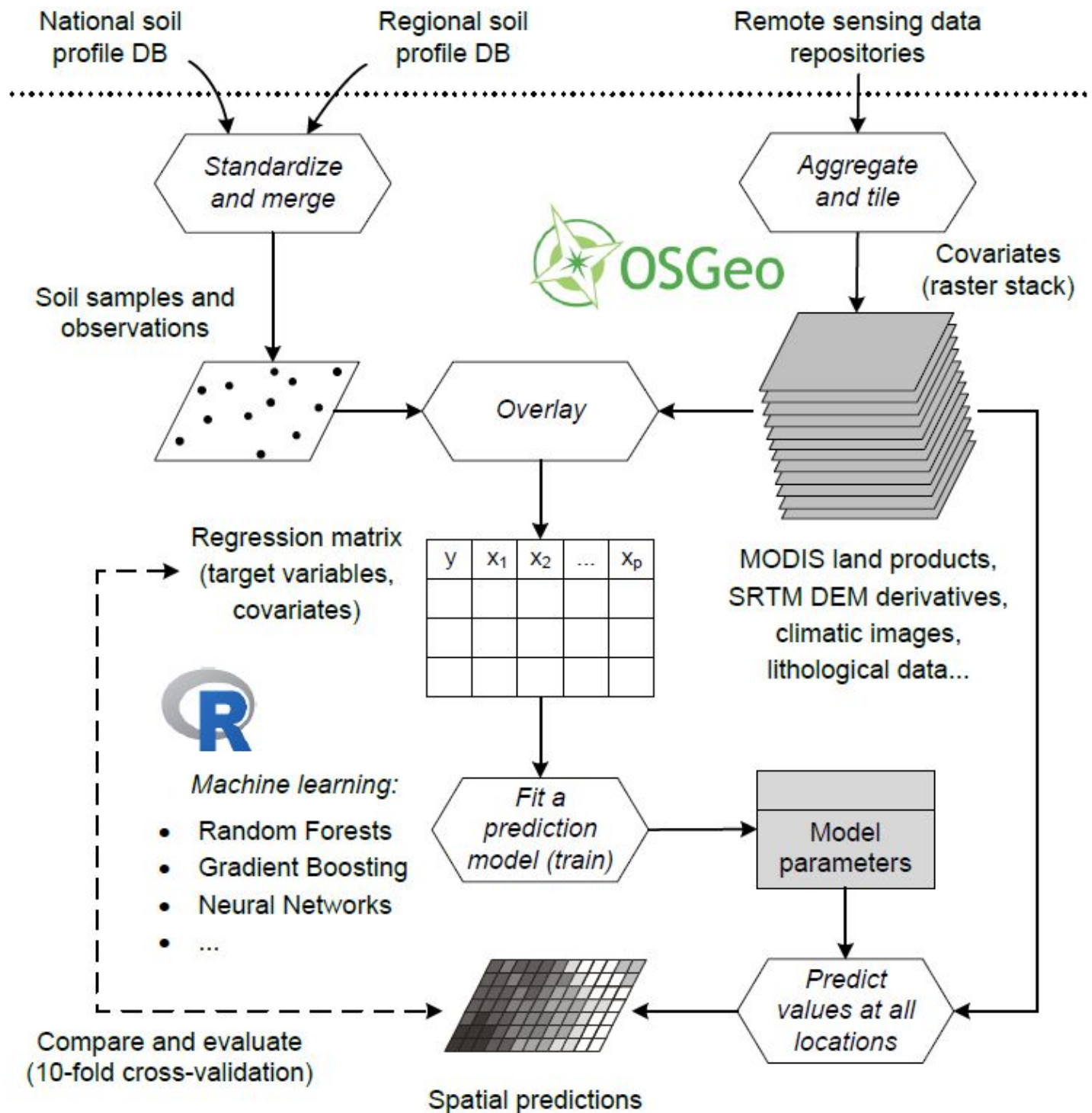
Machine learning as a framework for automated soil mapping



Methods

- 2D and 3D soil properties: **ensemble random forest and gradient boosting** (ranger, xgboost)
- soil types: **ensemble random forest and nnet::multinom**
- Cross-validation, post-processing, pseudo-observations





SoilGrids are possible
especially thanks to authors
of: ranger, xgboost, caret,
raster, nnet, SAGA GIS, GDAL,
Geoserver...



ranger: A Fast Implementation of Random Forests for High Dimensional Data in C++ and R

Marvin N. Wright
Universität zu Lübeck

Andreas Ziegler
Universität zu Lübeck,
University of KwaZulu-Natal

Abstract

We introduce the C++ application and R package **ranger**. The software is a fast implementation of random forests for high dimensional data. Ensembles of classification, regression and survival trees are supported. We describe the implementation, provide examples, validate the package with a reference implementation, and compare runtime and memory usage with other implementations. The new software proves to scale best with the number of features, samples, trees, and features tried for splitting. Finally, we show that **ranger** is the fastest and most memory efficient implementation of random forests to analyze data on the scale of a genome-wide association study.

Keywords: C++, classification, machine learning, R, random forests, **Rcpp**, recursive partitioning, survival analysis.



XGBoost: A Scalable Tree Boosting System

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ABSTRACT

Tree boosting is a highly effective and widely used machine learning method. In this paper, we describe a scalable end-to-end tree boosting system called XGBoost, which is used widely by data scientists to achieve state-of-the-art results on many machine learning challenges. We propose a novel sparsity-aware algorithm for sparse data and weighted quantile sketch for approximate tree learning. More importantly, we provide insights on cache access patterns, data compression and sharding to build a scalable tree boosting system. By combining these insights, XGBoost scales beyond billions of examples using far fewer resources than existing systems.

CCS Concepts

•Methodologies → Machine learning; •Information systems → Data mining;

Keywords

many applications. Tree boosting has been shown to give state-of-the-art results on many standard classification benchmarks [14]. LambdaMART [4], a variant of tree boosting for ranking, achieves state-of-the-art result for ranking problems. Besides being used as a stand-alone predictor, it is also incorporated into real-world production pipelines for ad click through rate prediction [13]. Finally, it is the de-facto choice of ensemble method and is used in challenges such as the Netflix prize [2].

In this paper, we describe XGBoost, a scalable machine learning system for tree boosting. The system is available as an open source package². The impact of the system has been widely recognized in a number of machine learning and data mining challenges. Take the challenges hosted by the machine learning competition site Kaggle for example. Among the 29 challenge winning solutions³ published at Kaggle's blog during 2015, 17 solutions used XGBoost. Among these solutions, eight solely used XGBoost to train the model, while most others combined XGBoost with neural nets in en-





Journal of Statistical Software

November 2008, Volume 28, Issue 5.

<http://www.jstatsoft.org/>

Building Predictive Models in R Using the caret Package

Max Kuhn
Pfizer Global R&D

Abstract

The **caret** package, short for classification and regression training, contains numerous tools for developing predictive models using the rich set of models available in R. The package focuses on simplifying model training and tuning across a wide variety of modeling techniques. It also includes methods for pre-processing training data, calculating variable importance, and model visualizations. An example from computational chemistry is used to illustrate the functionality on a real data set and to benchmark the benefits of parallel processing with several types of models.

Keywords: model building, tuning parameters, parallel processing, R, **NetWorkSpaces**.

Results



They would have been interested in this...



Vasili Dokuchaev

The Russian School

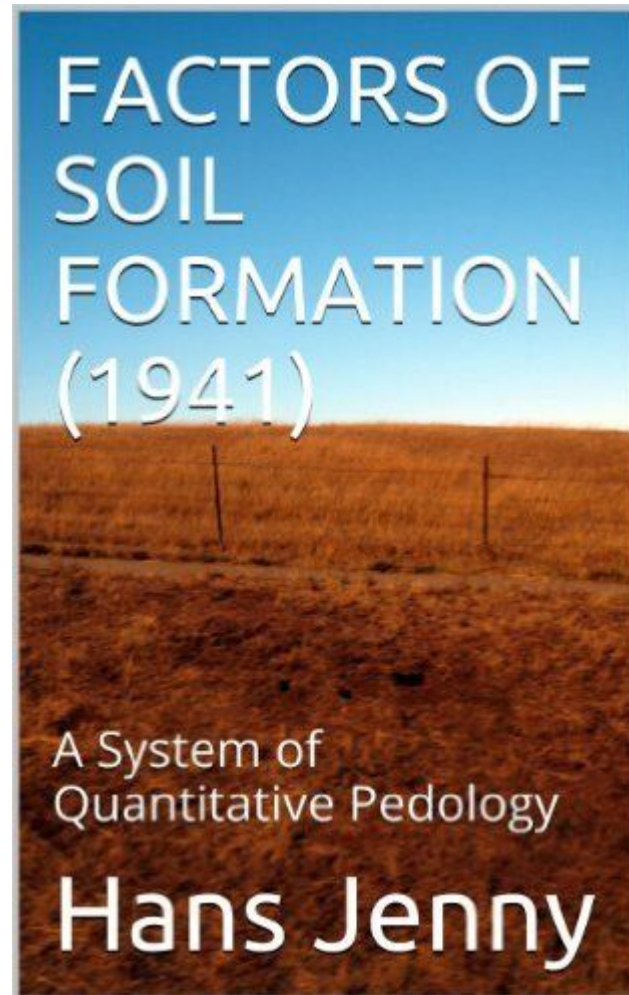
Soil forming factors



Soil forming processes

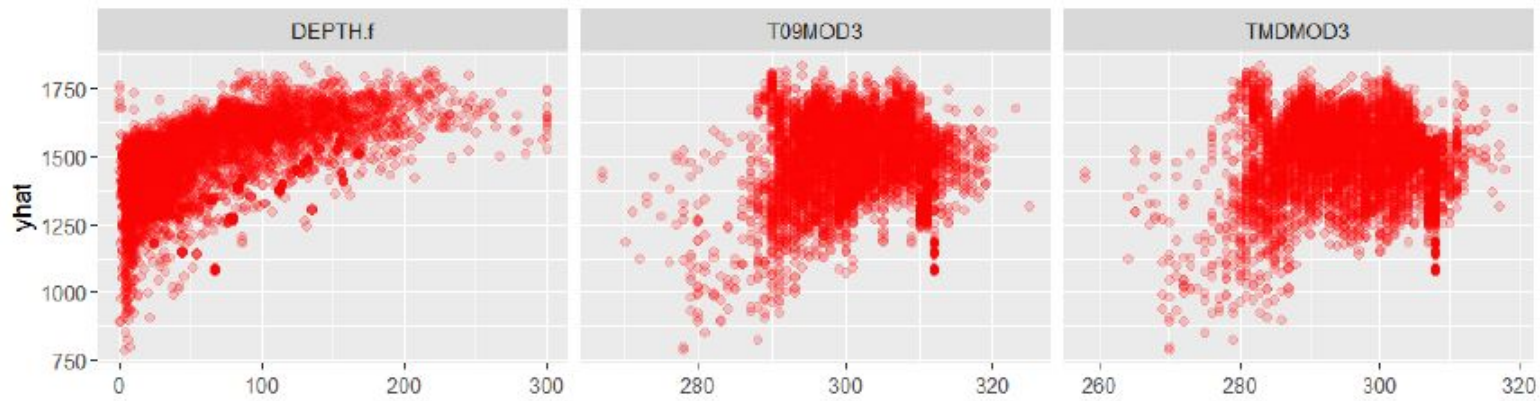


Different Soils

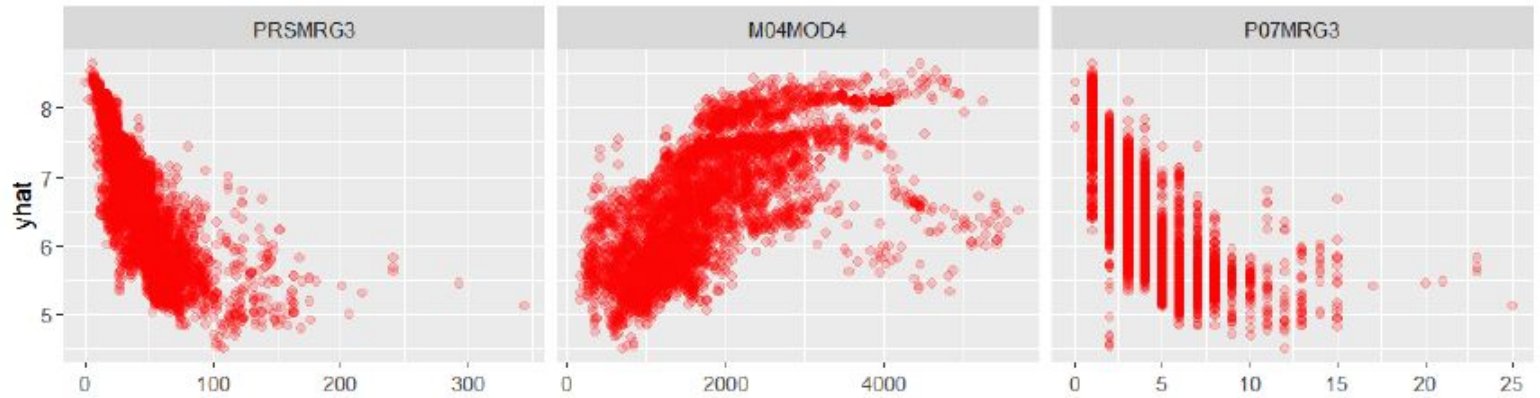


World Soil Information

**Bulk
density**



Soil pH



**Soil
organic
carbon**

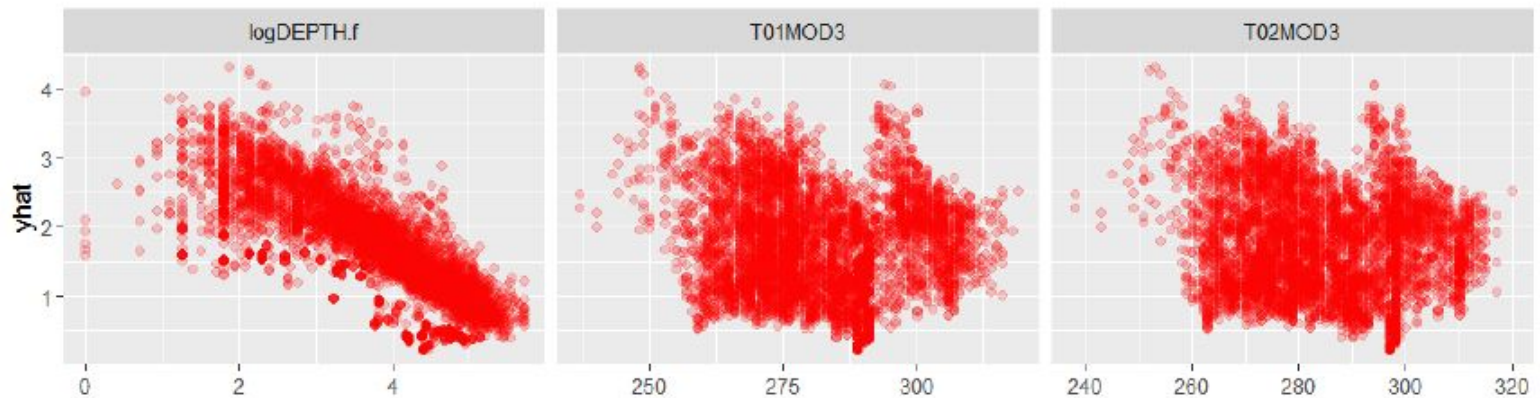


Figure 6. Examples of fitted relationships for bulk density (above), pH (middle) and soil organic carbon (below). Plots show target variables and top three most important covariates as reported by the random forest model. DEPTH.f is the depth from soil surface, T09MOD3 is mean monthly temperature for September, TMDMOD3 is mean annual temperature, PRSMRG3 is total annual precipitation, M04MOD4 is mean monthly MODIS NIR band reflectance, P07MRG3 is mean monthly precipitation for July, T01MOD3 is mean monthly temperature for January, and

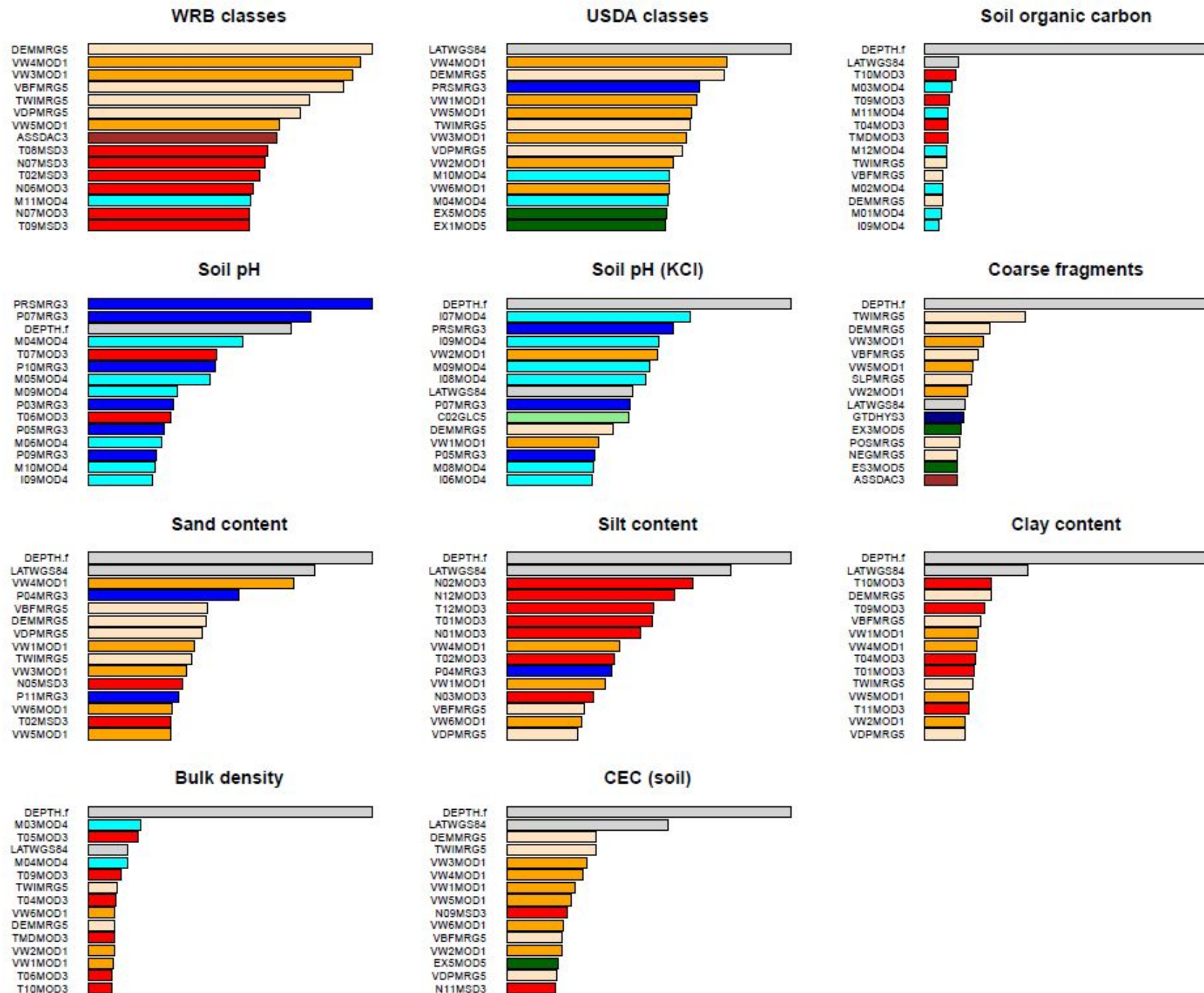


Figure 5. Fitted variable importance plots for target variables. Generated as an average between using the ranger and xgboost packages, (for soil types results are based on the ranger model only). DEPTH.f is the depth from soil surface, T**MOD3 and N**MOD3 are mean monthly temperatures daytime and nighttime (red color), TWI, DEM, VBF and VDP are DEM-parameters (bisque color), M**MOD4 are mean

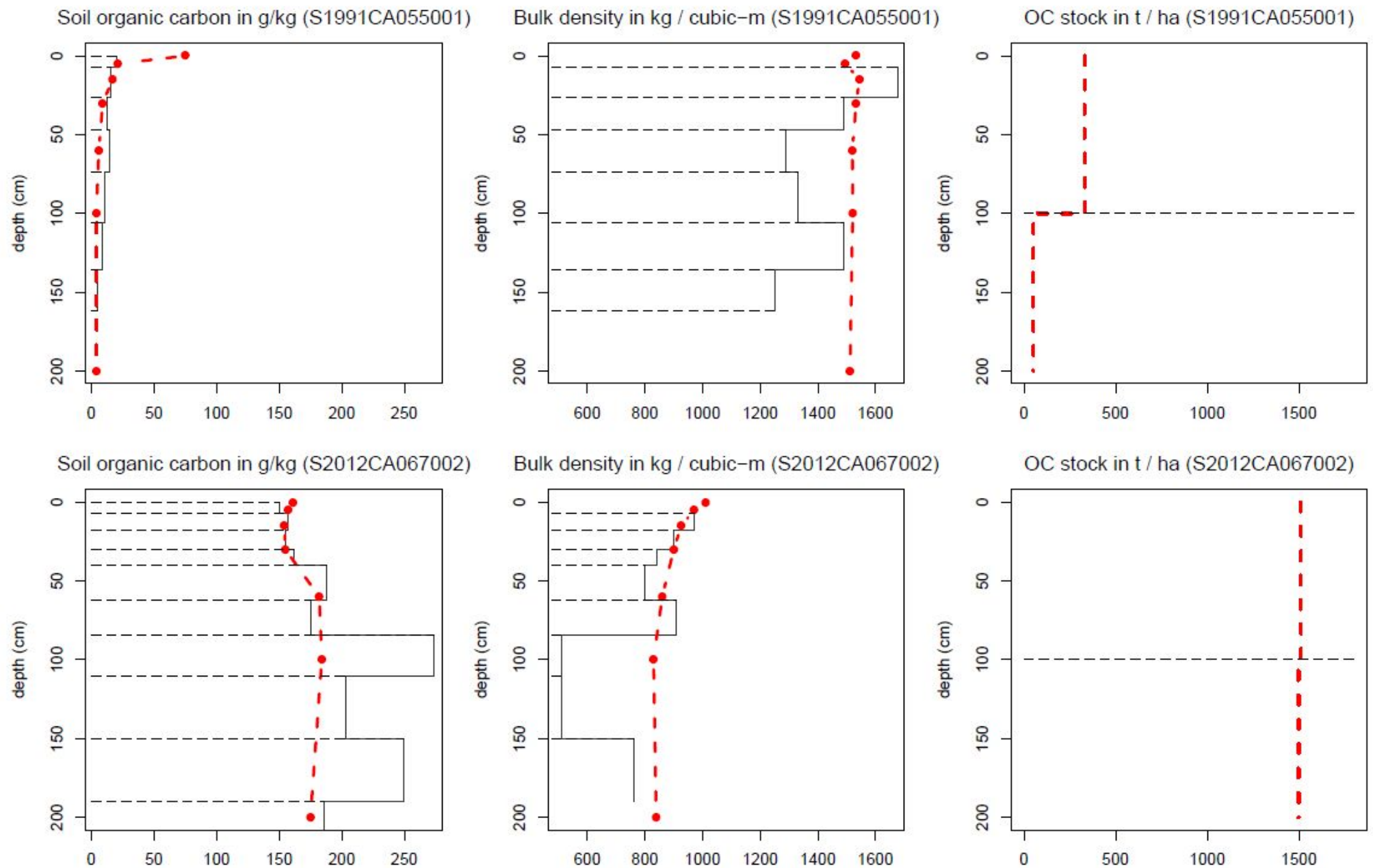
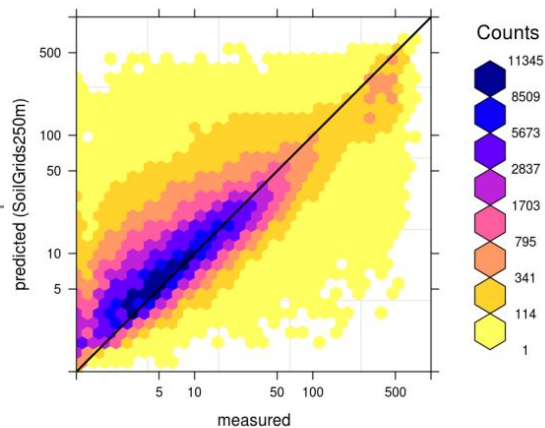
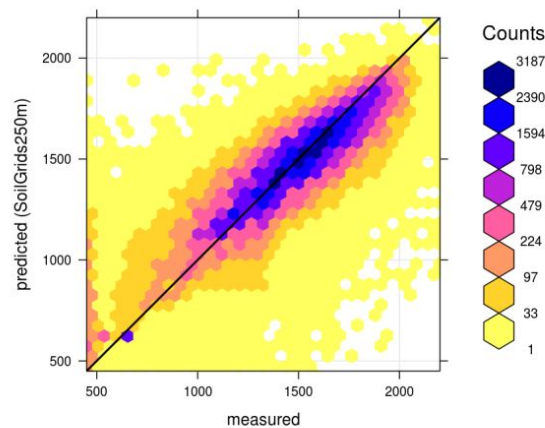


Figure 2. Example of soil variable-depth curves: original sampled soil profiles vs predicted values (SoilGrids) at seven standard depths (broken red line) and estimated soil organic carbon stock for depths 0–100 and 100–200 cm. Locations of points: mineral soil S1991CA055001 (-122.37°W, 38.25°N), and an organic soil profile S2012CA067002 (-121.62°W, 38.13°N).

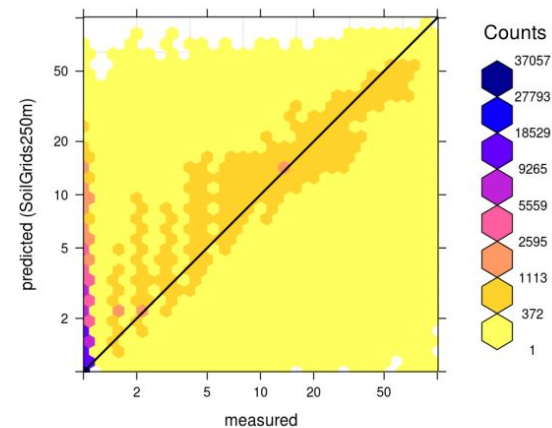
SOC in g/kg (CV R-squared: 0.64)



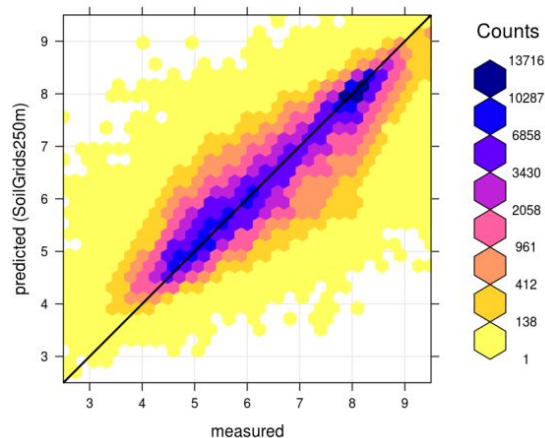
Bulk density (FE) in kg / m3 (CV R-squared: 0.76)



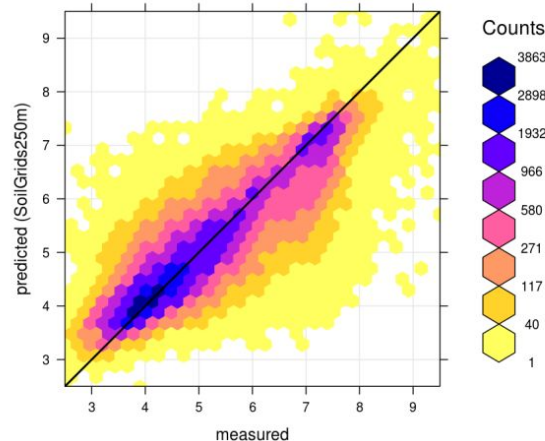
Coarse fragments in %vol (CV R-squared: 0.56)



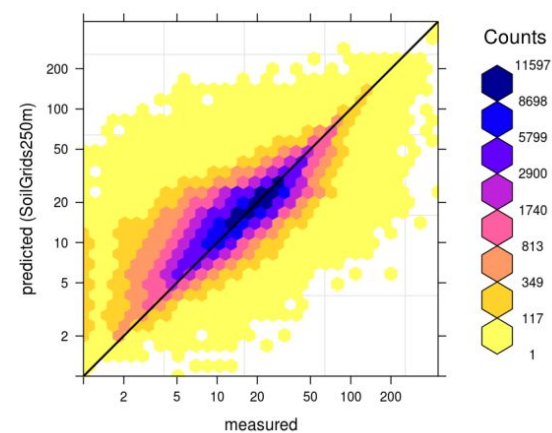
Soil pH x 10 in H2O (CV R-squared: 0.83)



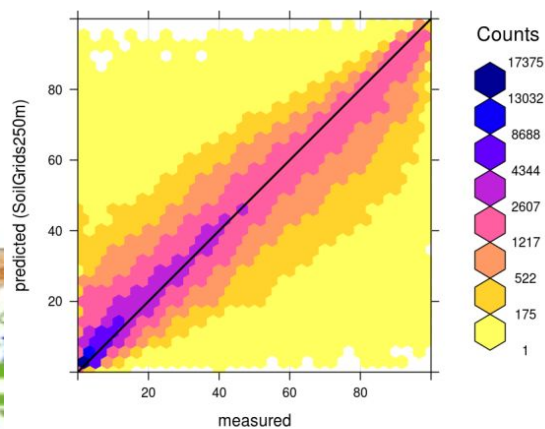
Soil pH x 10 in KCl (CV R-squared: 0.77)



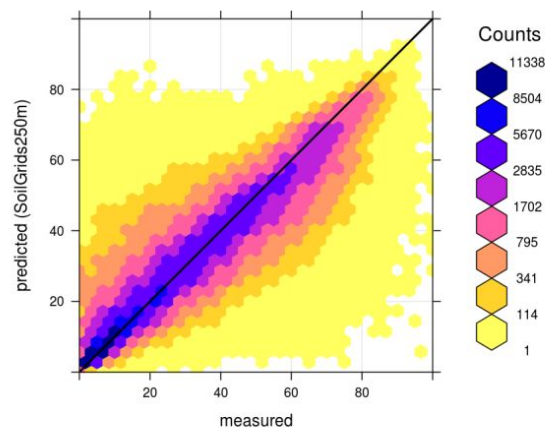
CEC soil in cmolc/kg (CV R-squared: 0.64)



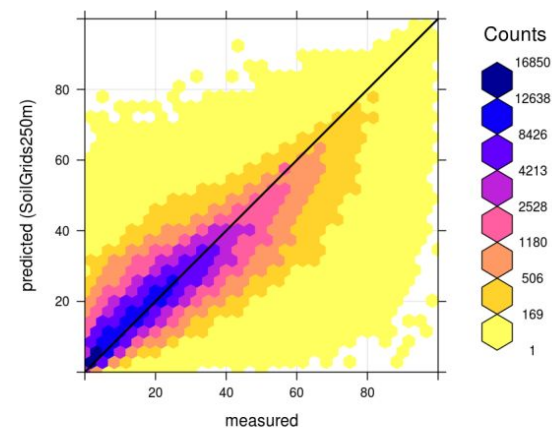
Sand fraction in % (CV R-squared: 0.79)



Silt fraction in % (CV R-squared: 0.79)



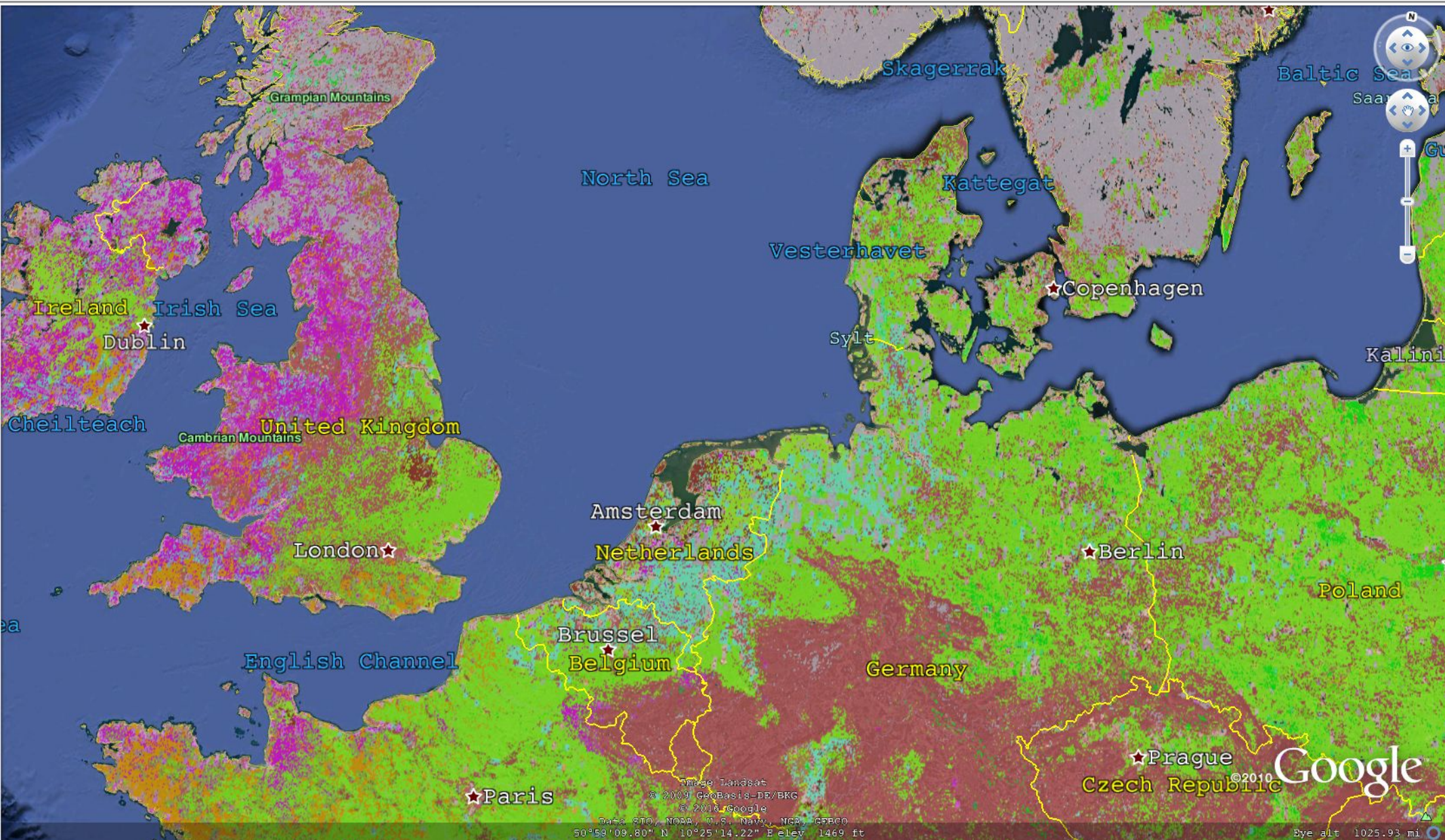
Clay fraction in % (CV R-squared: 0.73)



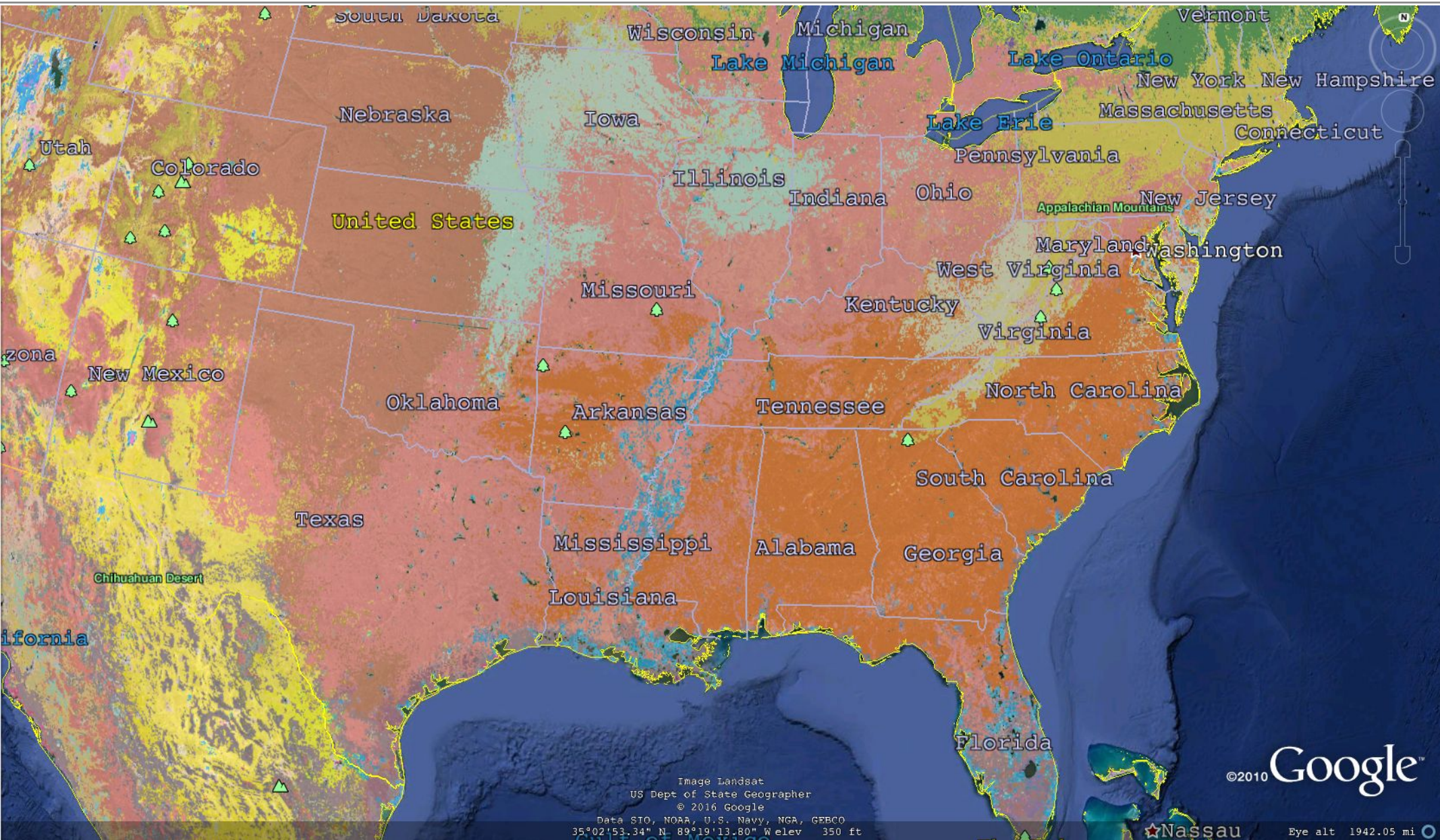
Maps

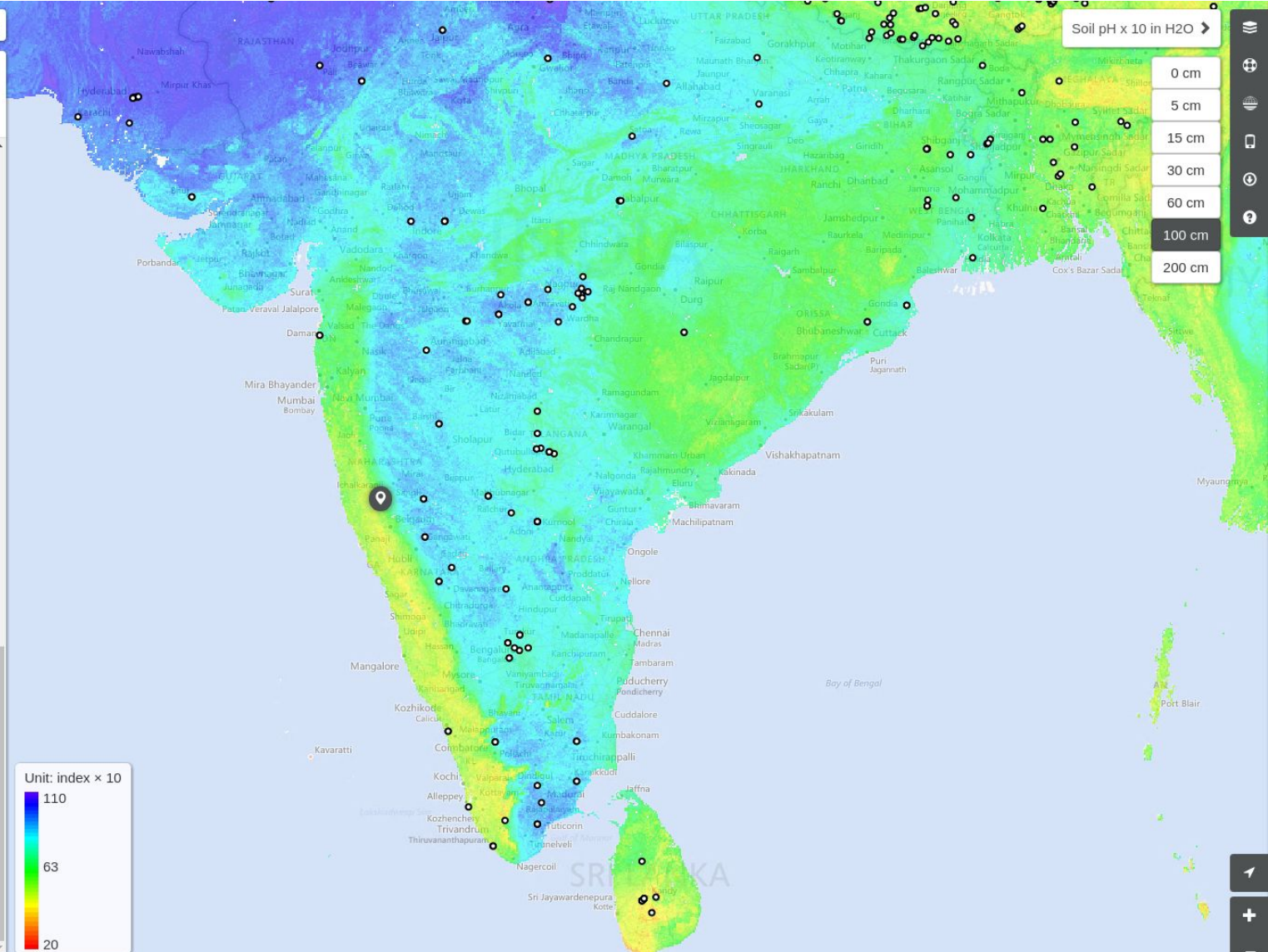
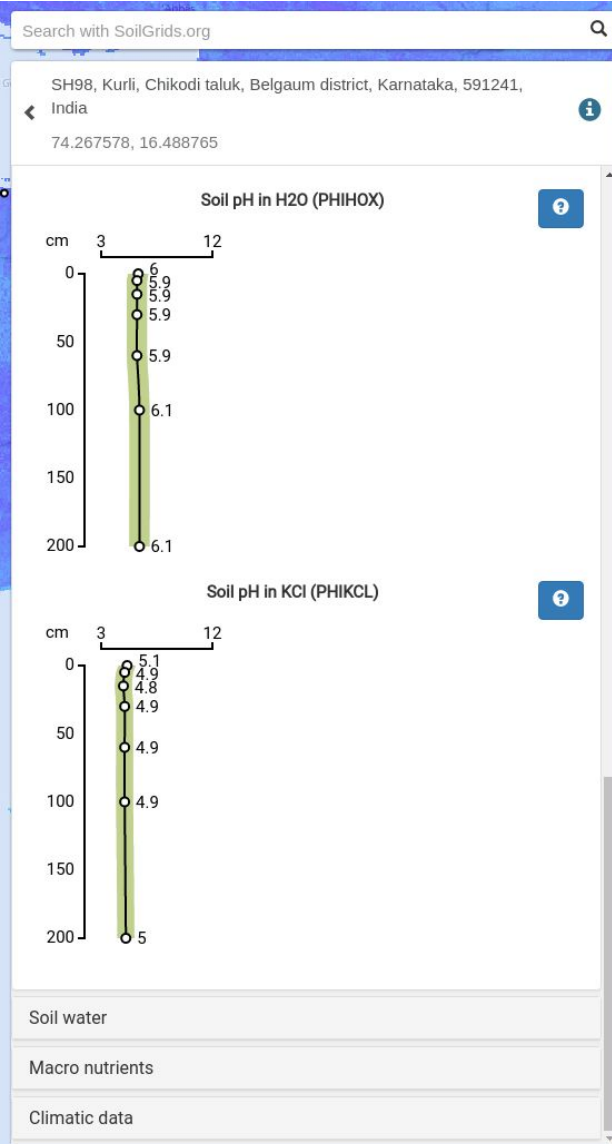


USDA suborders -> in Europe!

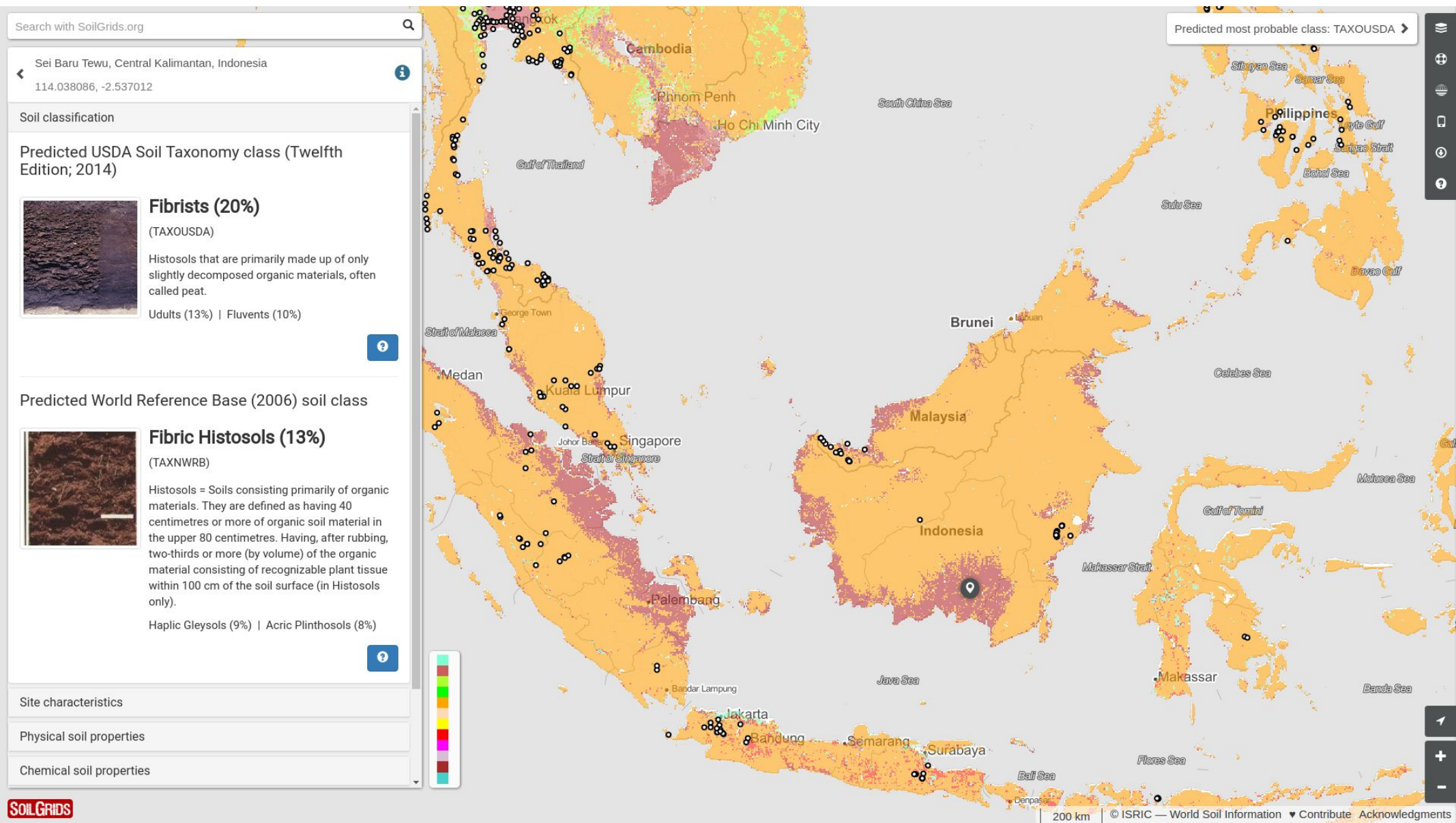


WRB 2nd level -> in USA!





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Opxyc, Aarhus Municipality, Central Denmark Region, Denmark

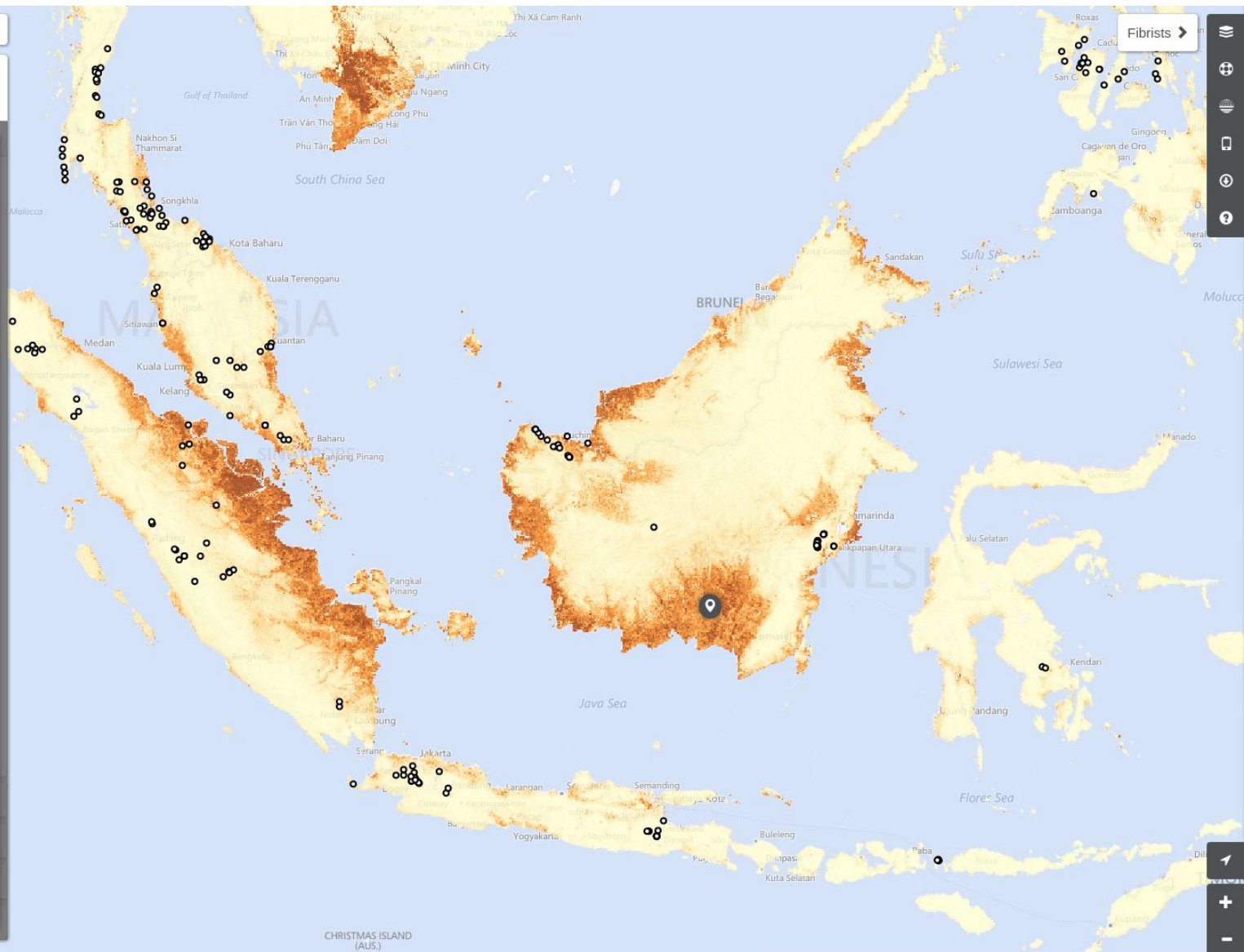


Sebangau Permai, Central Kalimantan, Indonesia



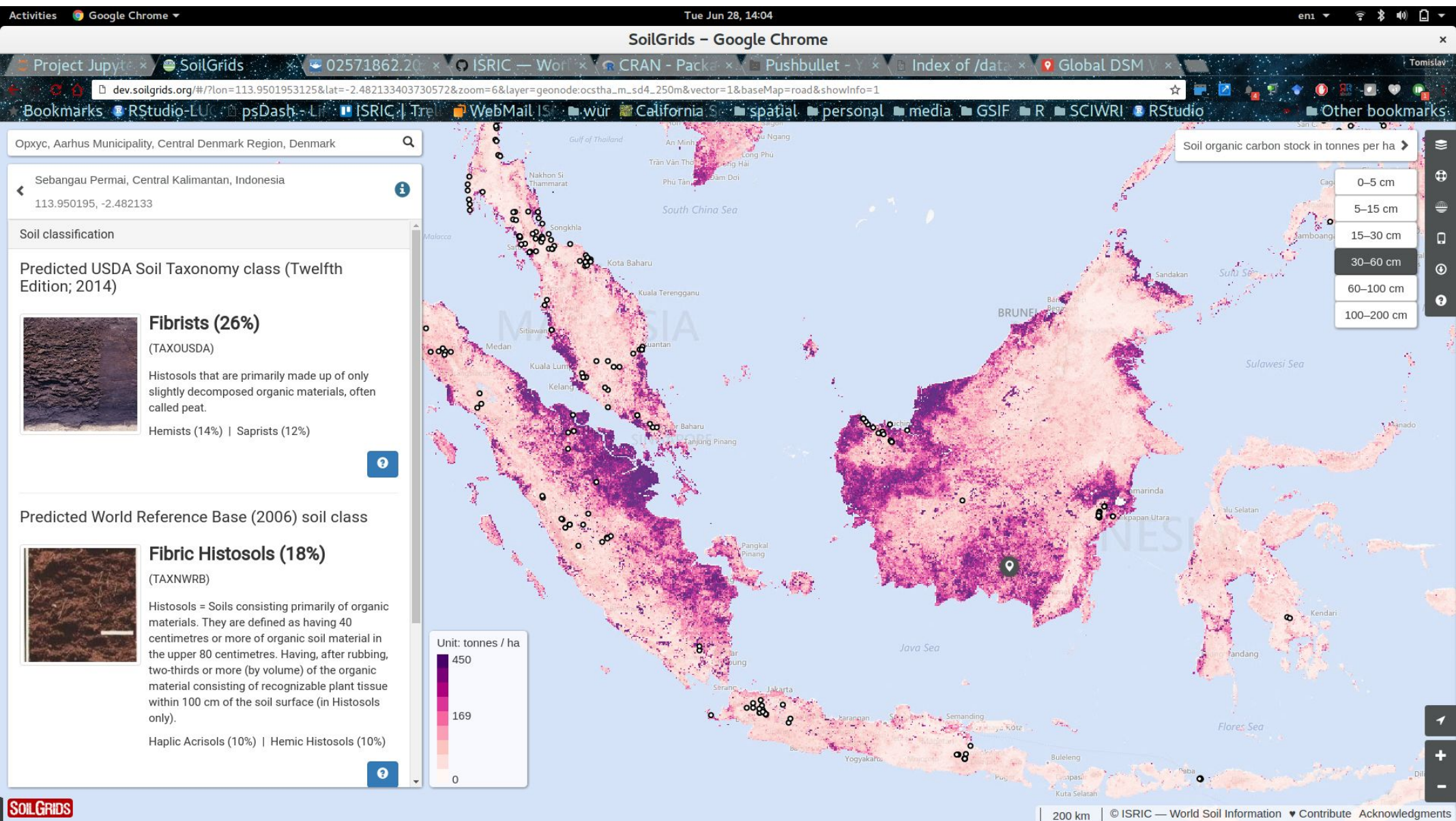
113.950195, -2.482133

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ADB BOROSAPRIST
T.M 10.22
XIV/1 Dal
42 O
Photo A.R. Aandahl

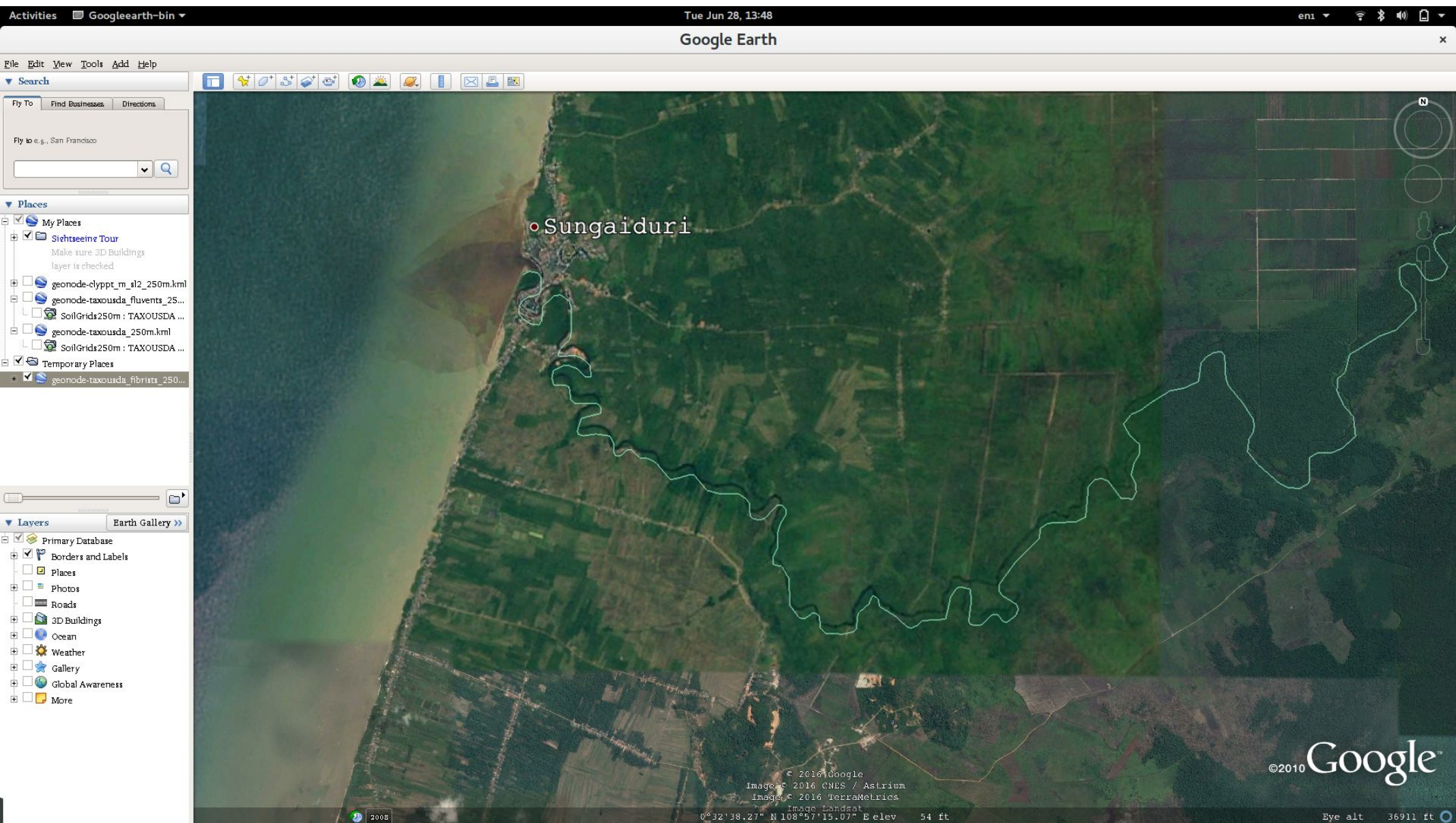


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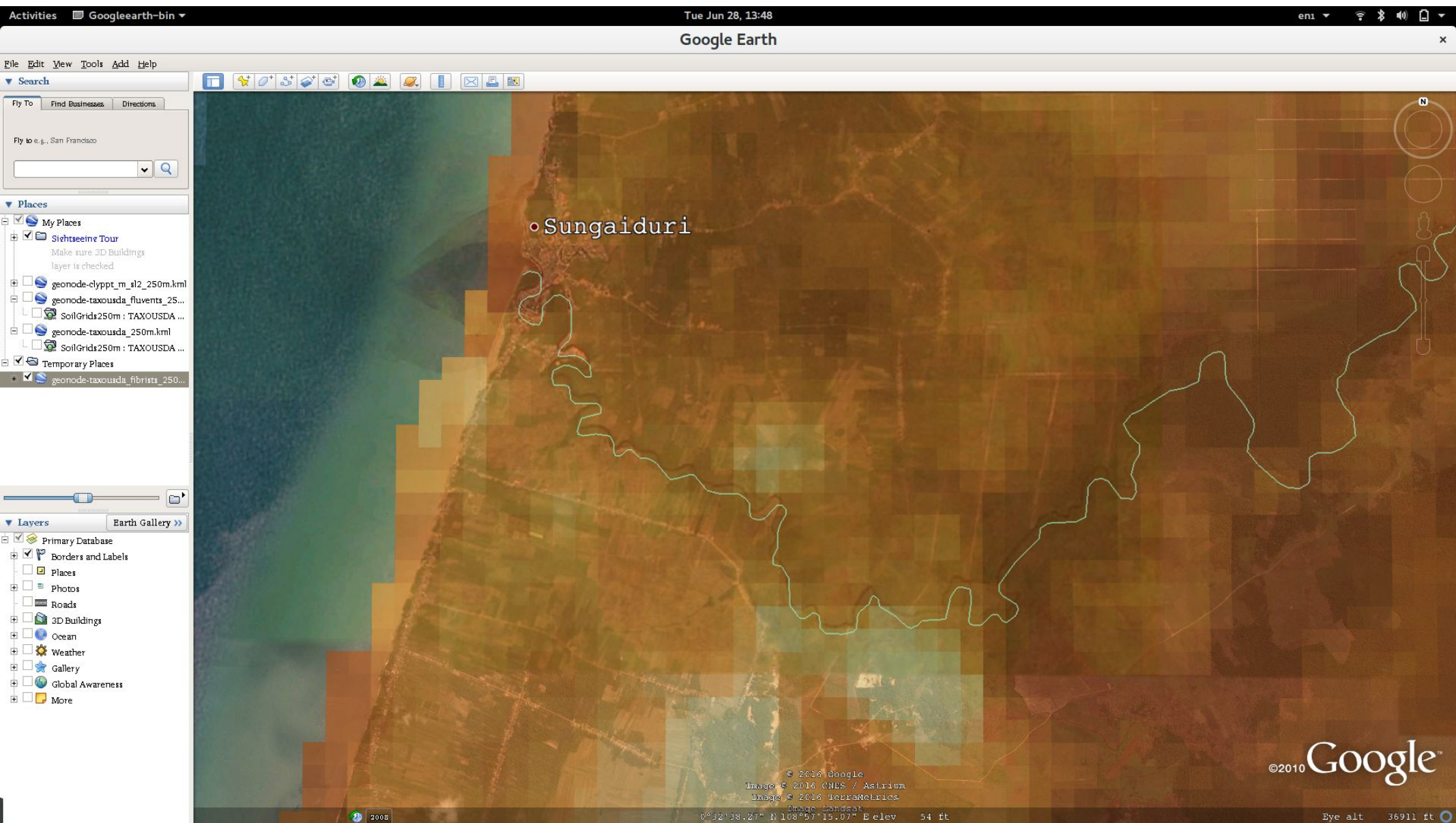




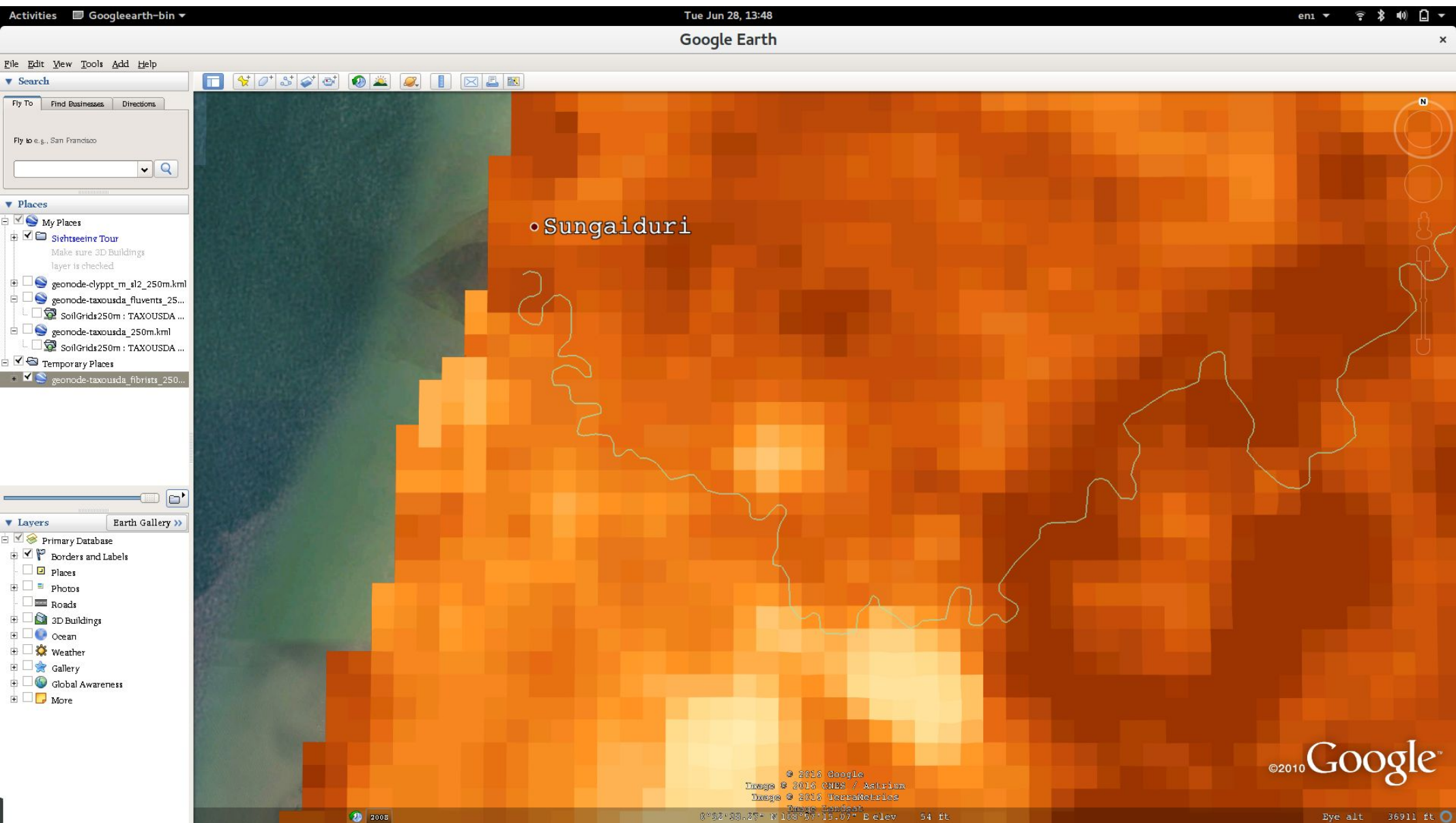
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Opqyc, Aarhus Municipality, Central Denmark Region, Denmark

Ontario, Canada
-88.066406, 54.927142

Soil classification

Site characteristics

Soil organic carbon stock in tonnes per ha (OCSTHA)

cm 0 500 1000 1500

0
50
100
150
200

Property	Value
Depth to bedrock (R horizon) up to 175 cm (BDRICM)	200 cm
Predicted probability of occurrence (0-100%) of R horizon (BDRLOG)	0%
Absolute depth to bedrock (BDTICM)	2894 cm
Drainage classes, based on FAO guidelines (DRAINFAO)	<NA>

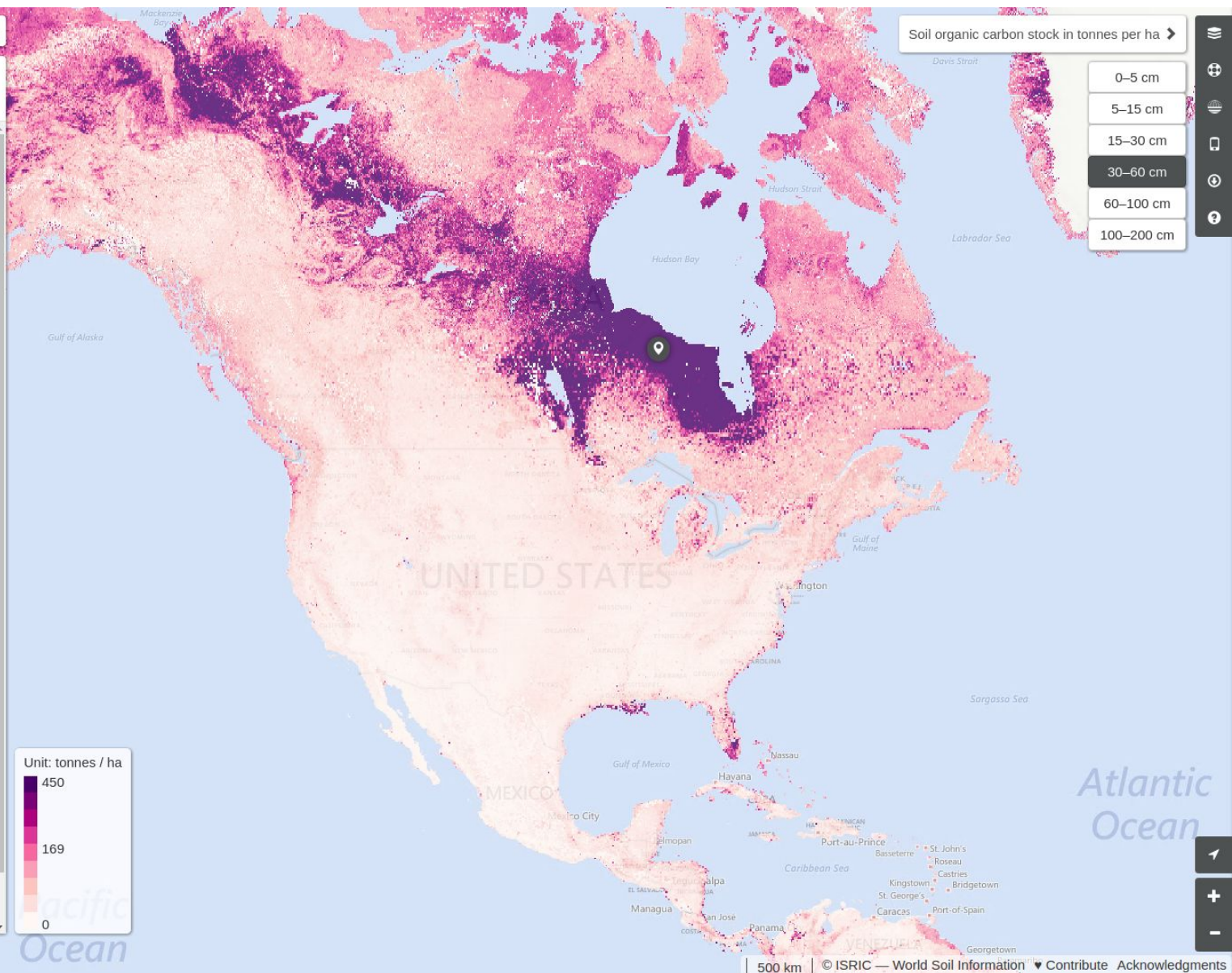
Physical soil properties

Chemical soil properties

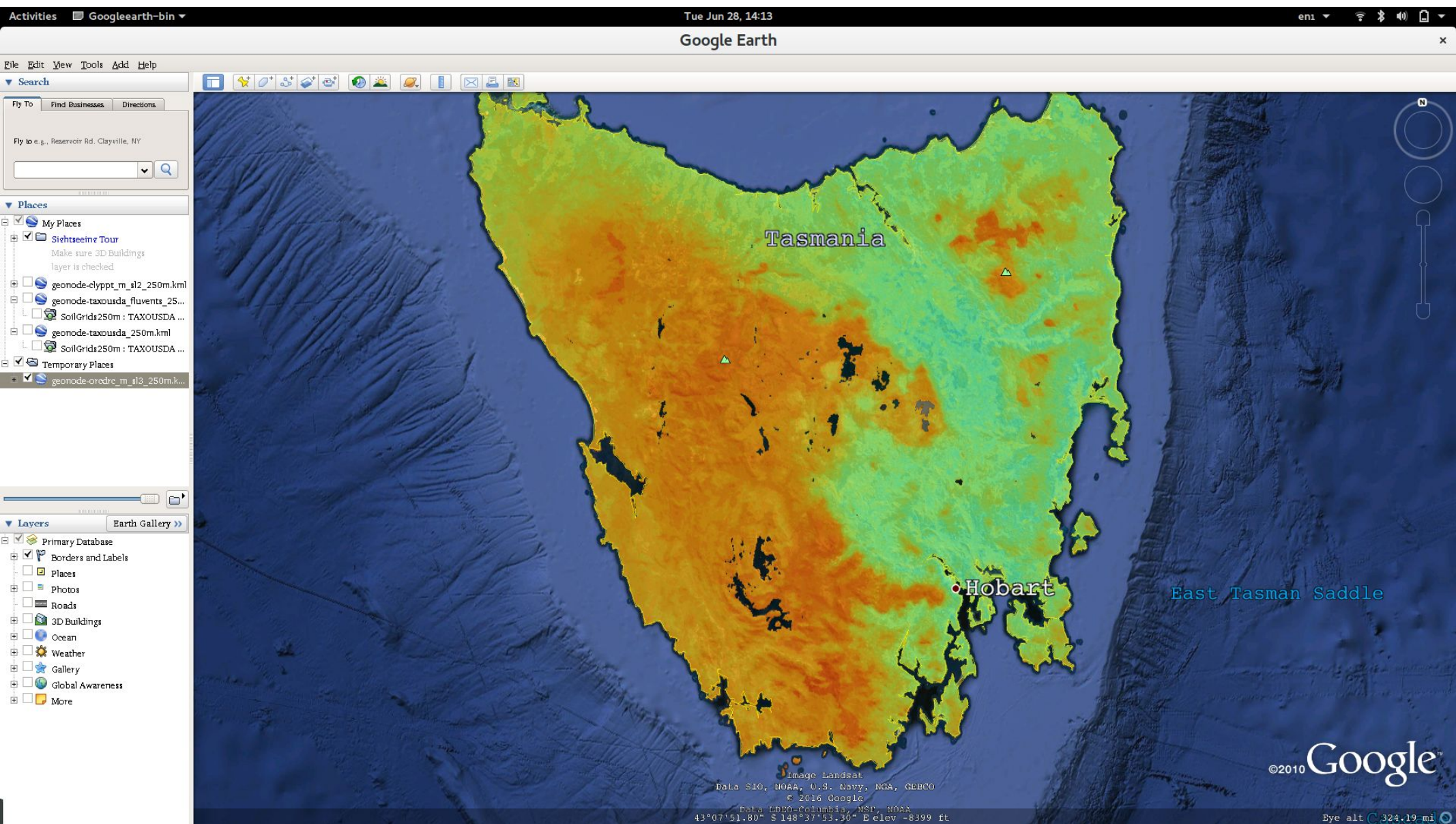
Soil water

Macro nutrients

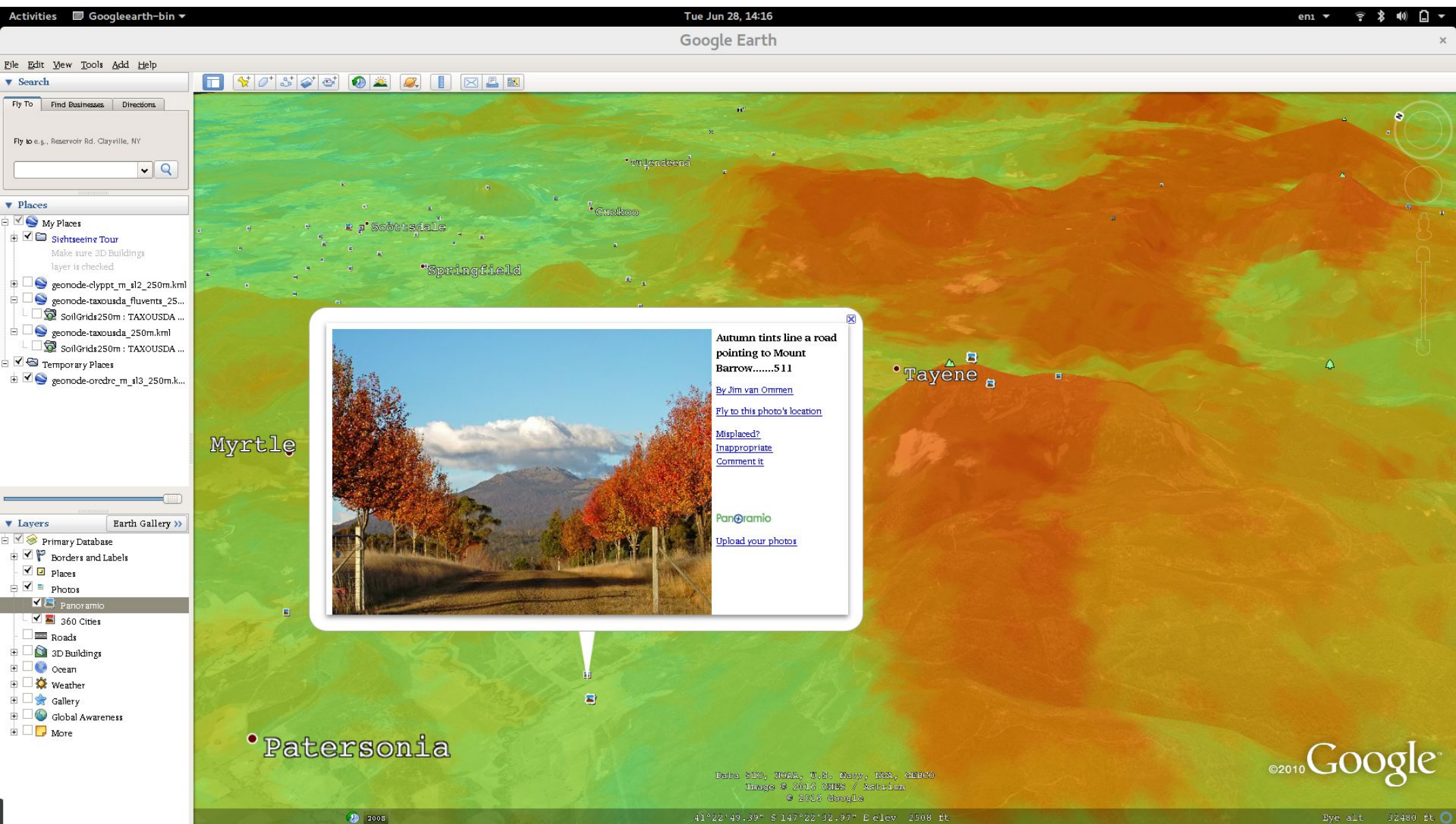
SOILGRIDS



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 - geonode:taxousta_250m
- Temporary Places

▼ Layers

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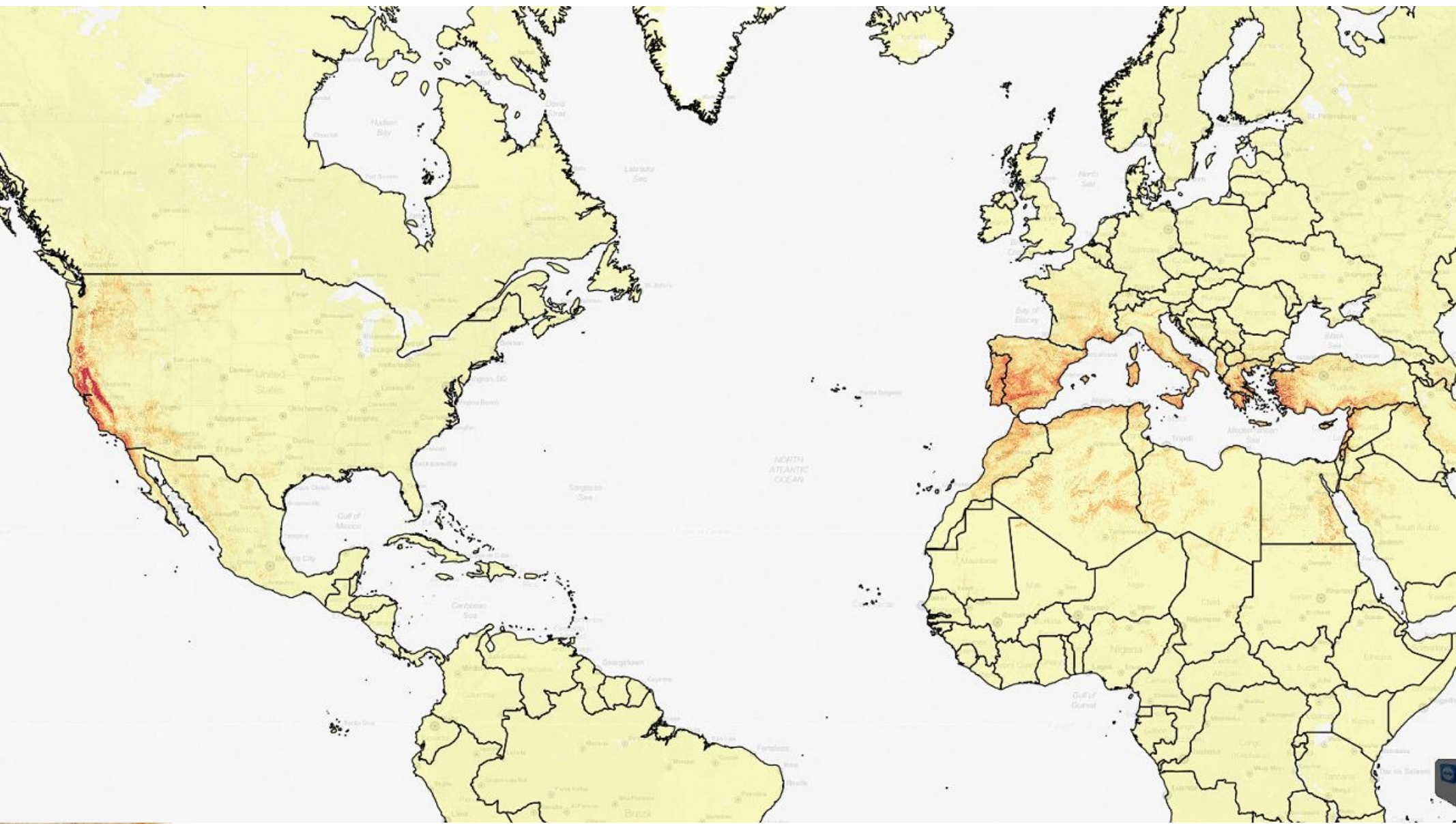
Image 2 of 4
US Dept of State
© 2006 Google
3°02'28.51" N 37°35'13.92" E Elev 5051 ft

Eye alt 25.64 mi



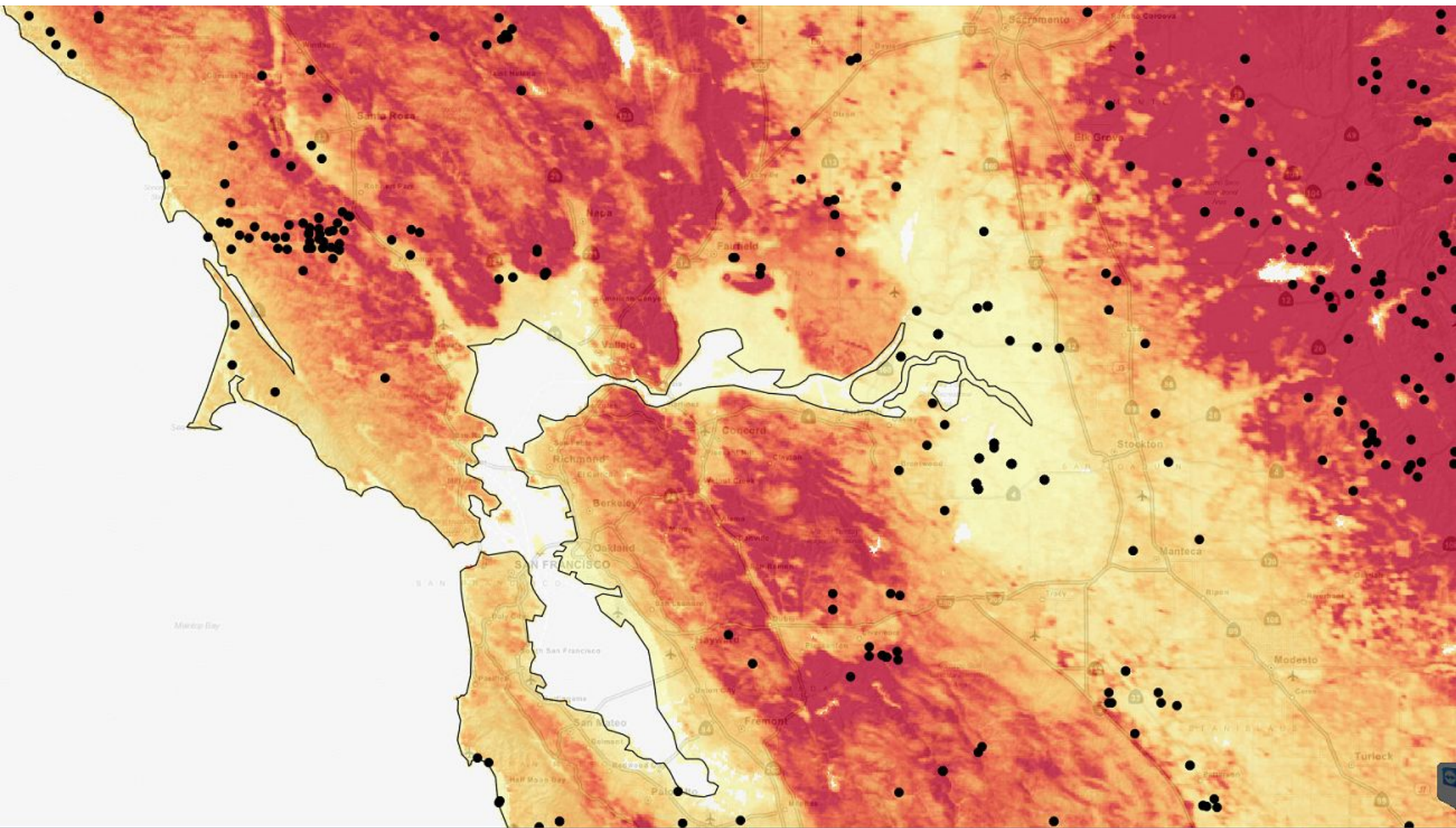
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Xeraľfs



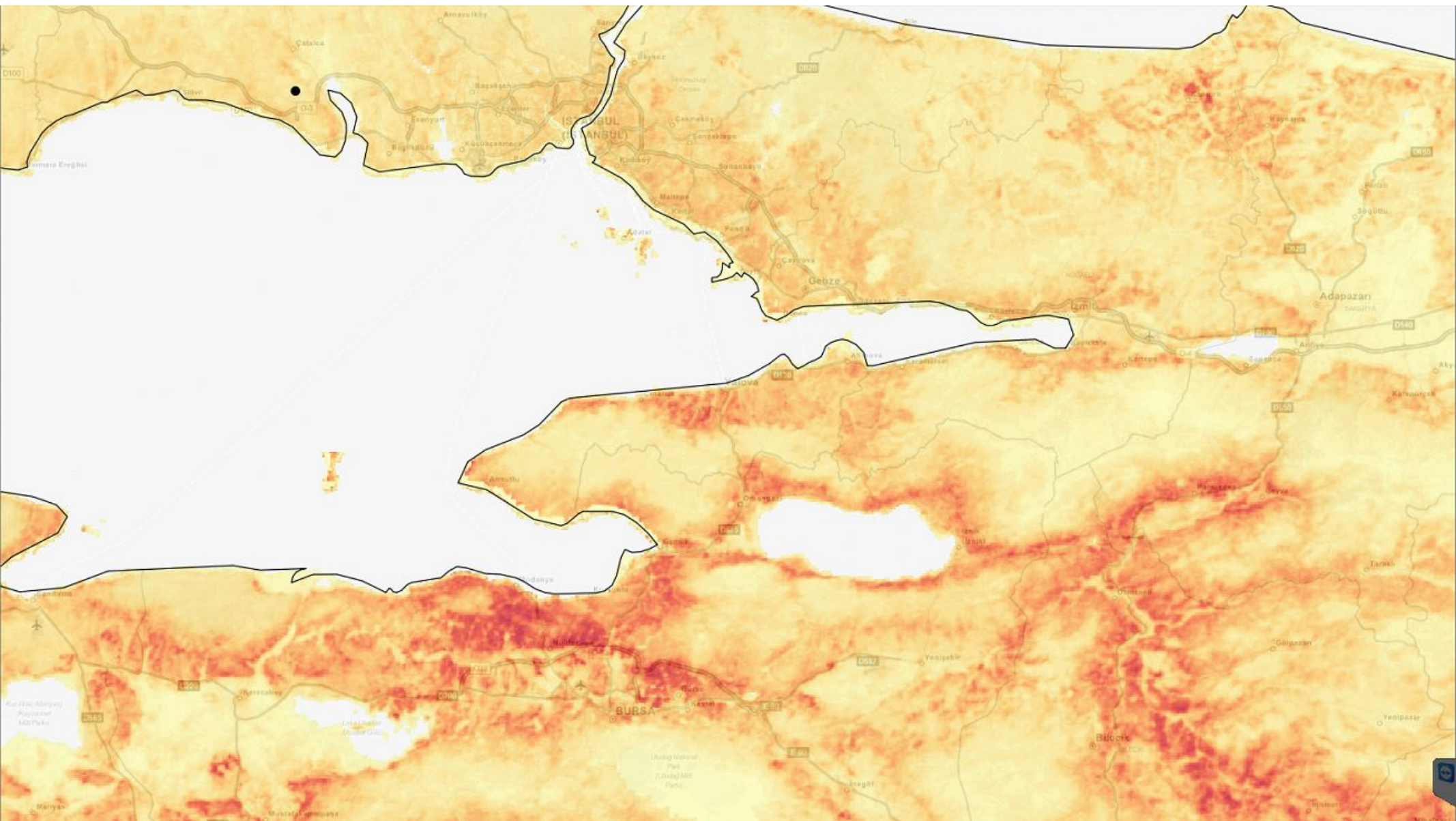
World Soil Information

Thanks to enough soil profiles from USA...



World Soil Information

... it is possible to map areas of similar soil/climate in Turkey!



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Conclusions



Conclusions

- Traditional soil surveyors got it right! — distribution of soil classes is mainly controlled by DEM morphometry (especially hydrological parameters).
- Soil classification and polygon models of soils seem to make sense — in many parts of the world we see "soil groupings i.e. **soil bodies**"... but there are also many transition zones and individual patches... so it is really a hybrid model that we need to use to represent spatial variation.
- In the machine learning framework, much more time needs to be spent on preparing data / experimental design.



Conclusions II

- Our predictions could still be improved: **the most critical is to prepare a better (covariate) map of parent material and drainage classes.**
- We could also now "easily" go beyond 250 m (100 m, 30 m) because there is so much remote sensing data in the public domain.
- SoilGrids250m (global models) can be merged with local predictions to produce best unbiased predictions of soil properties.





Uncertainty in soil data can outweigh climate impact signals in global crop yield simulations

Christian Folberth, Rastislav Skalský, Elena Moltchanova, Juraj Balkovič, Ligia B. Azevedo, Michael Obersteiner & Marijn van der Velde

[Affiliations](#) | [Contributions](#) | [Corresponding author](#)

Nature Communications 7, Article number: 11872 | doi:10.1038/ncomms11872

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PDF



Citation



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Article metrics

Abstract

[Abstract](#) • [Introduction](#) • [Results](#) • [Discussion](#) • [Methods](#) • [Additional information](#) • [References](#) • [Acknowledgements](#) • [Author information](#) • [Supplementary information](#)

Global gridded crop models (GGCMs) are increasingly used for agro-environmental assessments and estimates of climate change impacts on food production. Recently, the influence of climate data and weather variability on GGCM outcomes has come under detailed scrutiny, unlike the influence of soil data. Here we compare yield variability caused by the soil type selected for GGCM simulations to weather-induced yield variability. Without fertilizer application, soil-type-related yield variability generally outweighs the simulated inter-annual variability in yield due to weather. Increasing applications of fertilizer and irrigation reduce this variability until it is practically negligible. Importantly, estimated climate change effects on yield can be either negative or positive depending on the chosen soil type. Soils thus have the capacity to either buffer or amplify these impacts. Our findings call for improvements in soil data available for crop modelling and more explicit accounting for soil variability in GGCM

Authors with **Loop profiles** **beta**



Michael Obersteiner

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Portsmouth, United Kingdom

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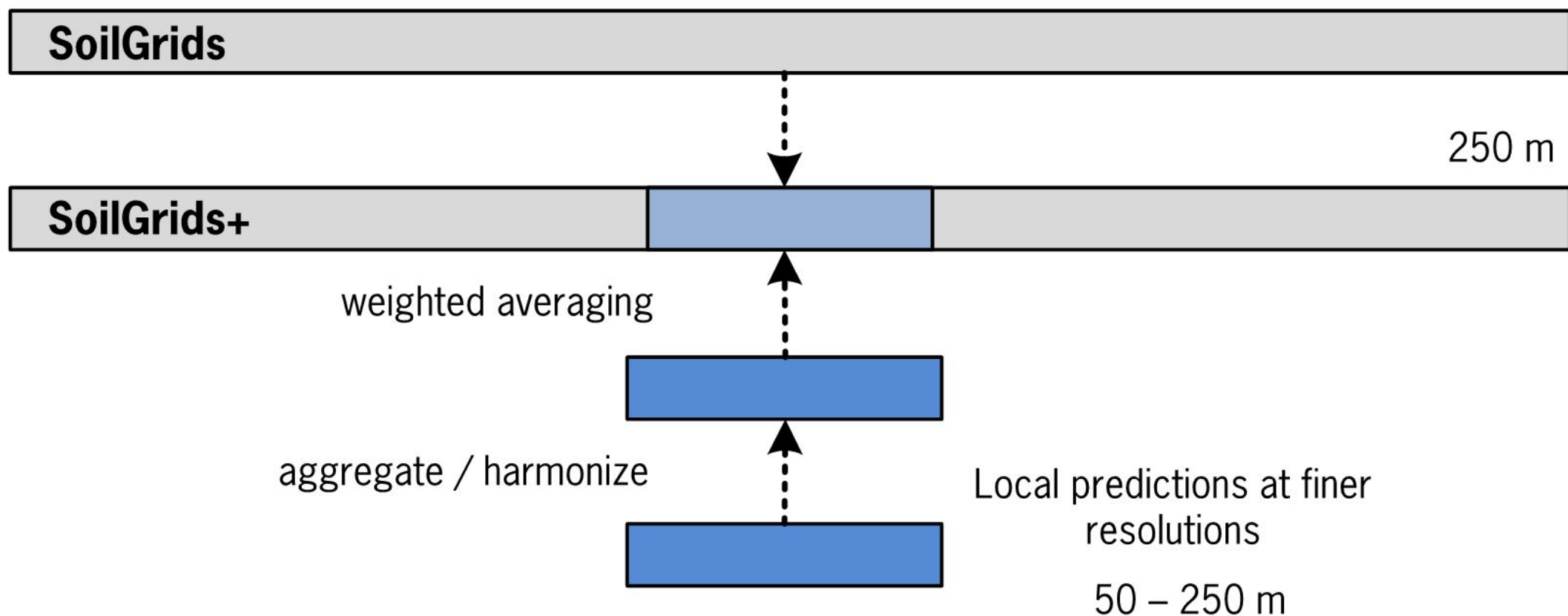
Discover more

Most read

[Near-global freshwater-specific](#)

SoilGrids+

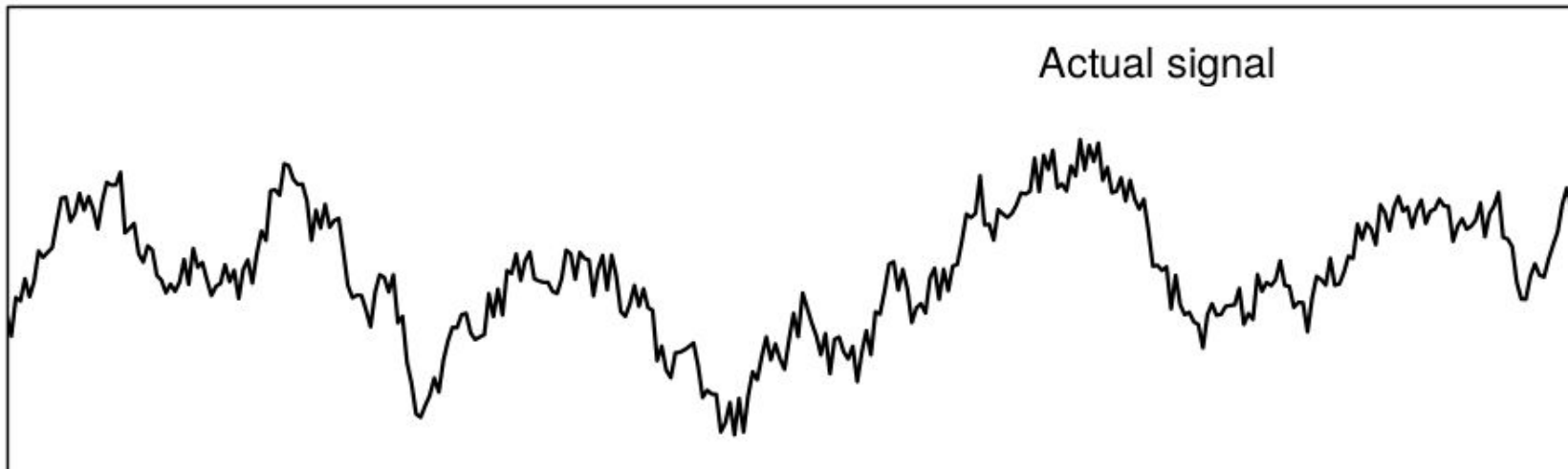
Global, consistent, complete and up-to-date gridded soil information



World Soil Information

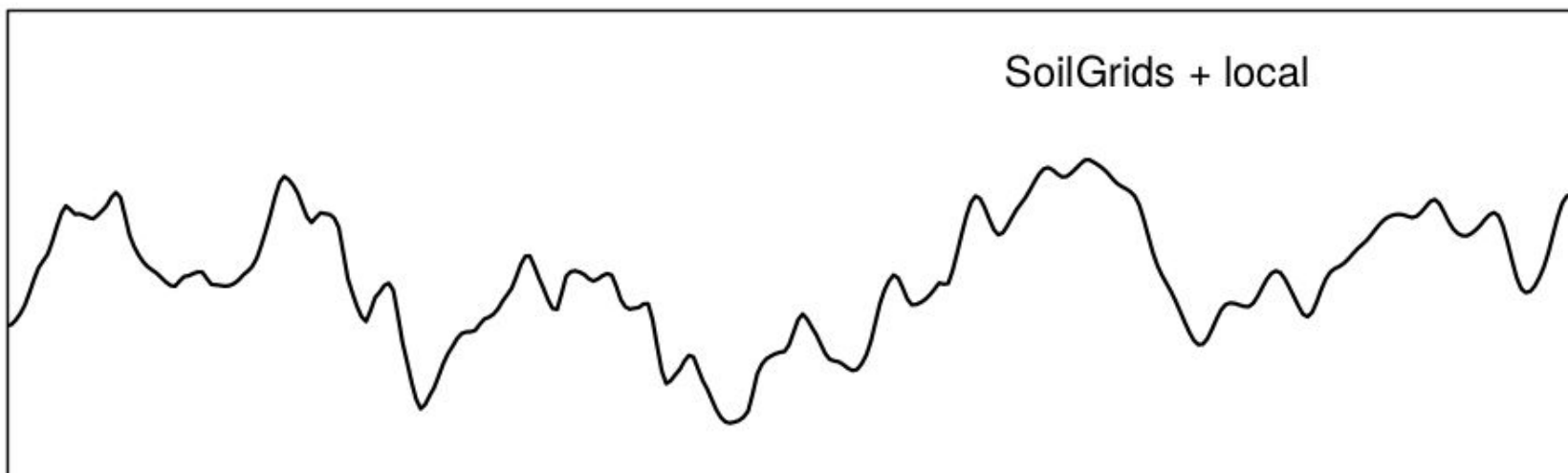
$S_2 + S_1 + e$

Actual signal



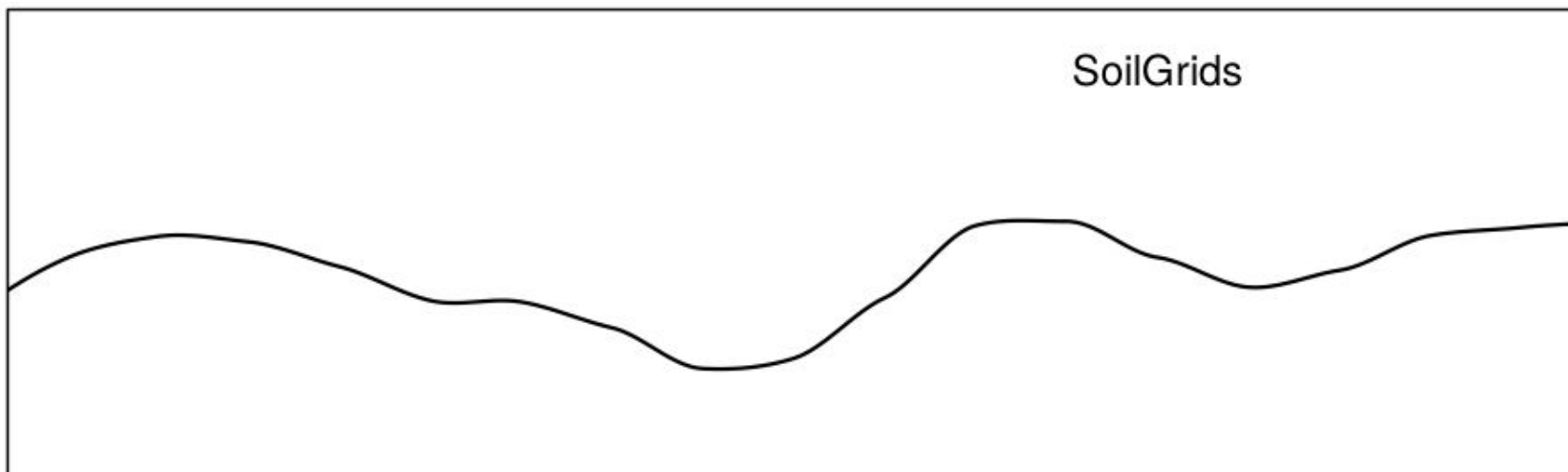
$S_2 + S_1$

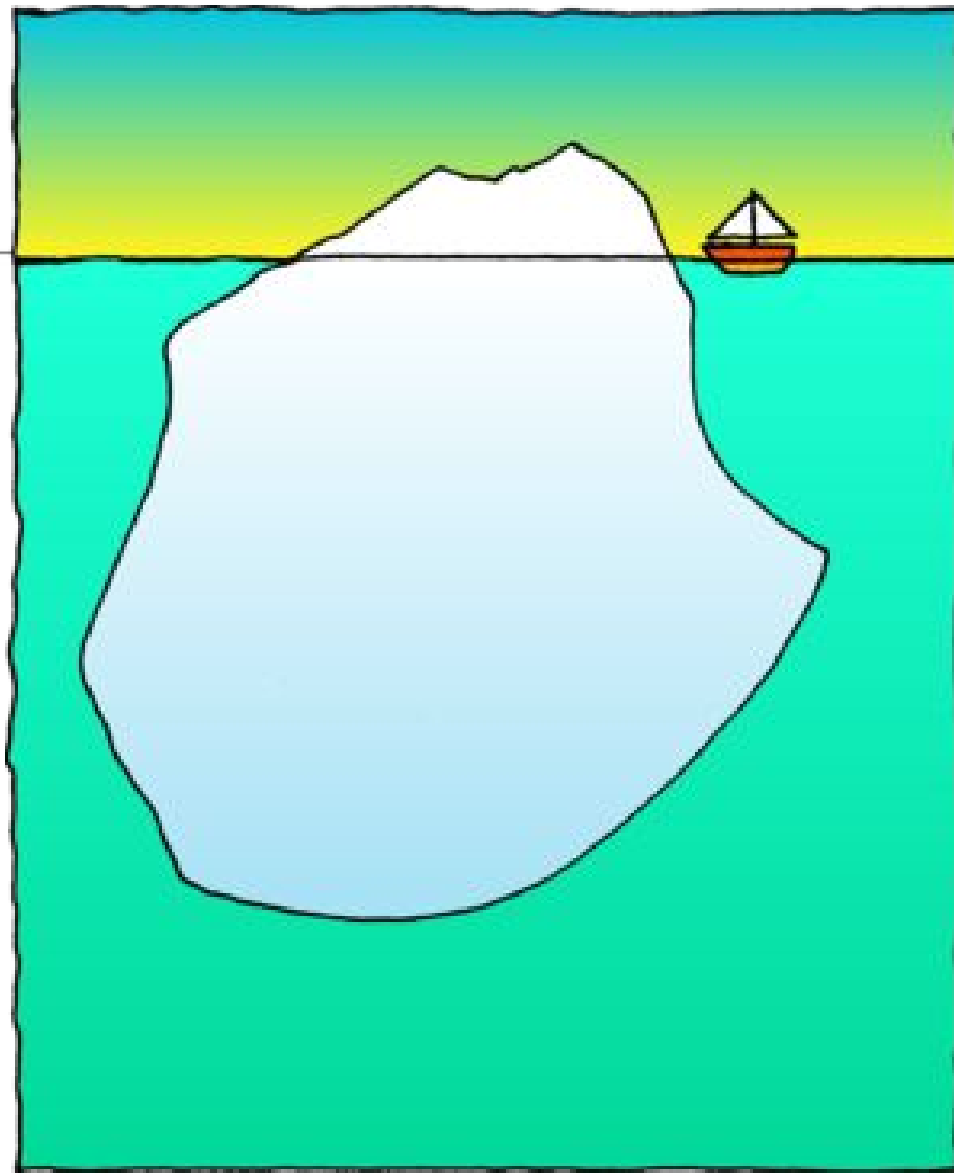
SoilGrids + local



S_2

SoilGrids





**We still
know very
little about
world soils!**

God's Word is like an iceberg-
there is more truth unseen than seen

Resolution
(metres)

The moderate-resolution imaging spectroradiometer (**MODIS**)

250

Shuttle Radar topography missions (**SRTMGL3**)

100

Landsat 8 TIRS bands

Sentinel-1,2
(bands 1, 9, 10)

50

ALOS Global Digital
Surface Model

AW3D30

SRTMGL1

Landsat 8 MS bands

Sentinel-1,2
(bands 5, 6, 7, 8a, 11, 12)

30

WorldDEM

10

1

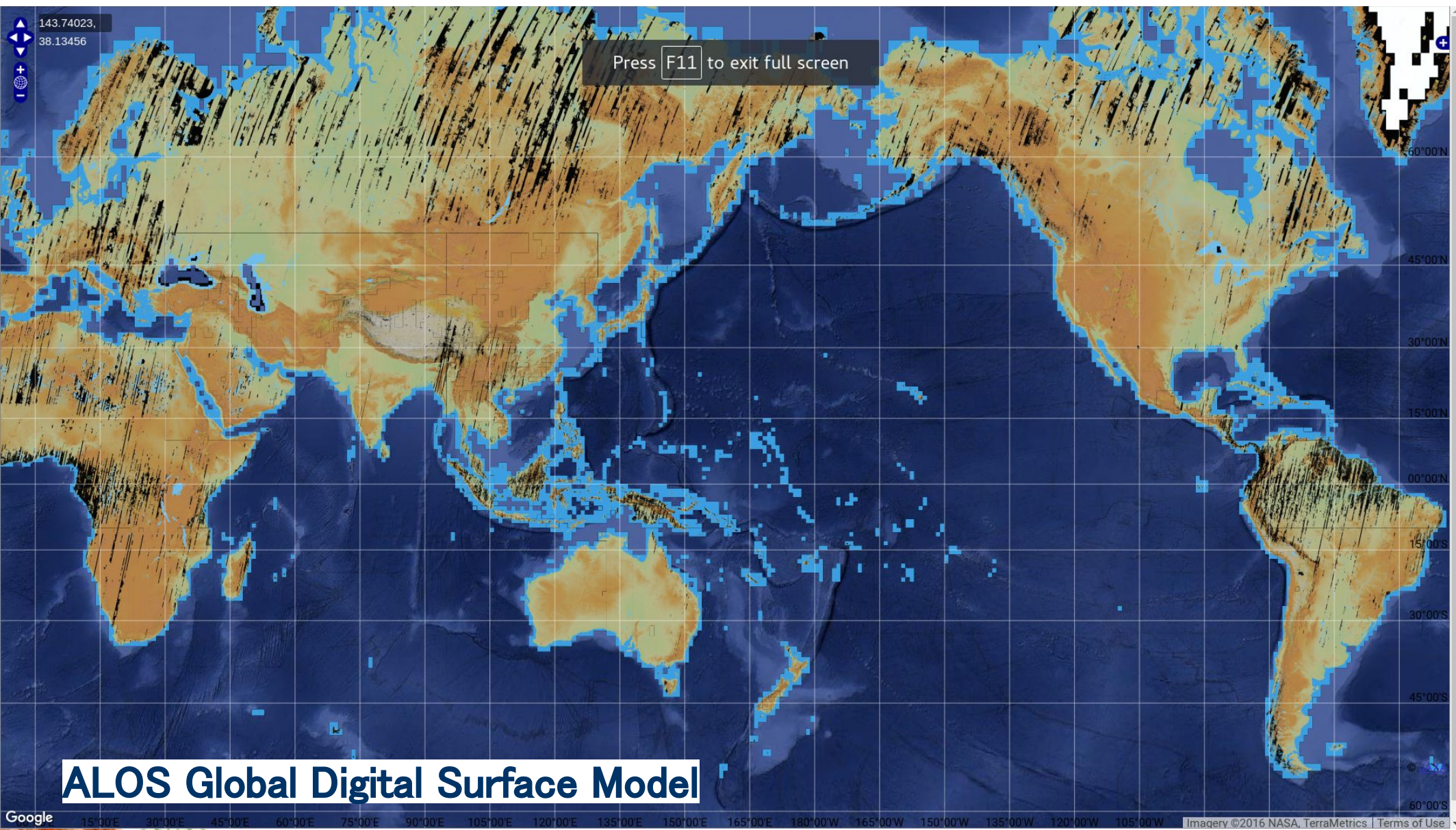
2000

2010

2020



Towards 100 m, 30 m resolution...



World Soil Information

Get ready for the **Soil Data Revolution!**



World Soil Information